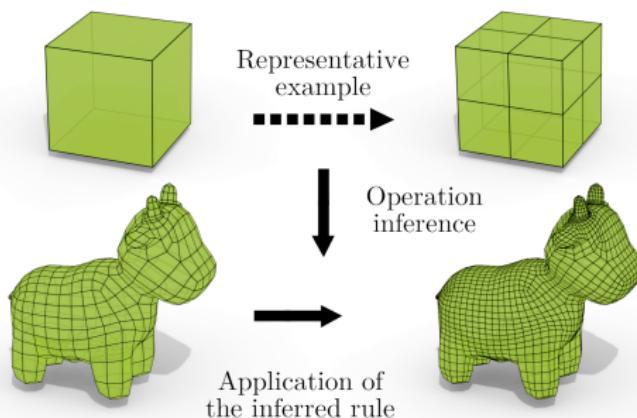


An approach for inferring geometric expressions in topology-based geometric modeling

Revisited as a program synthesis problem



Romain Pascual

Pascale Le Gall, Hakim Belhaouari,
and Agnès Arnould

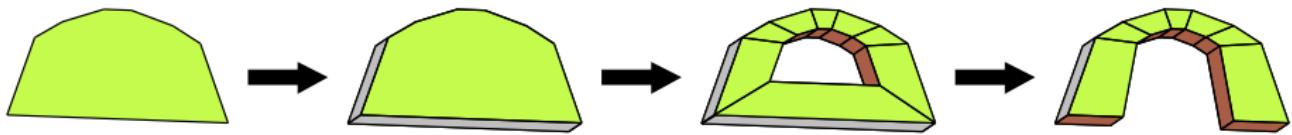
October 6, 2023
FM&AI working group at LMF

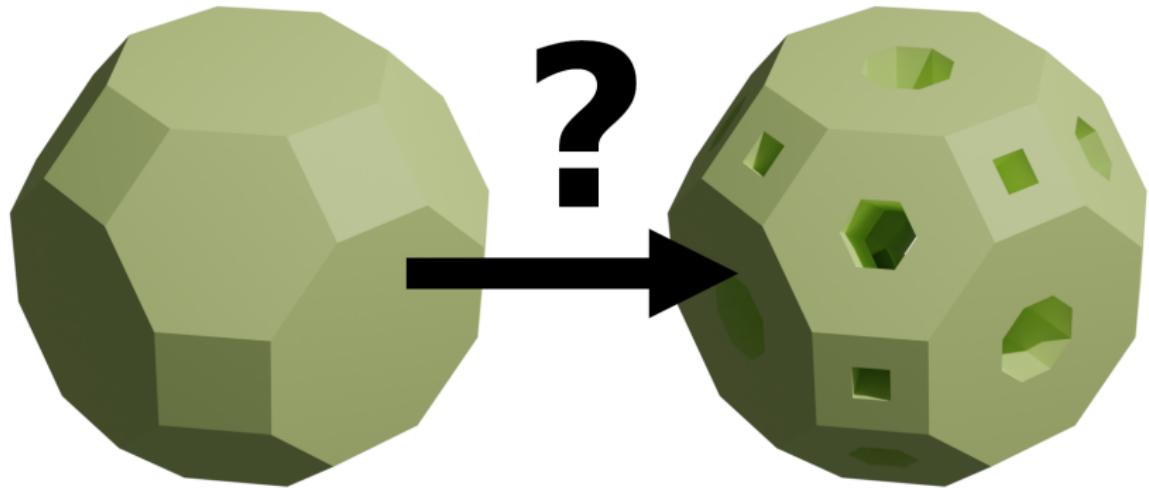


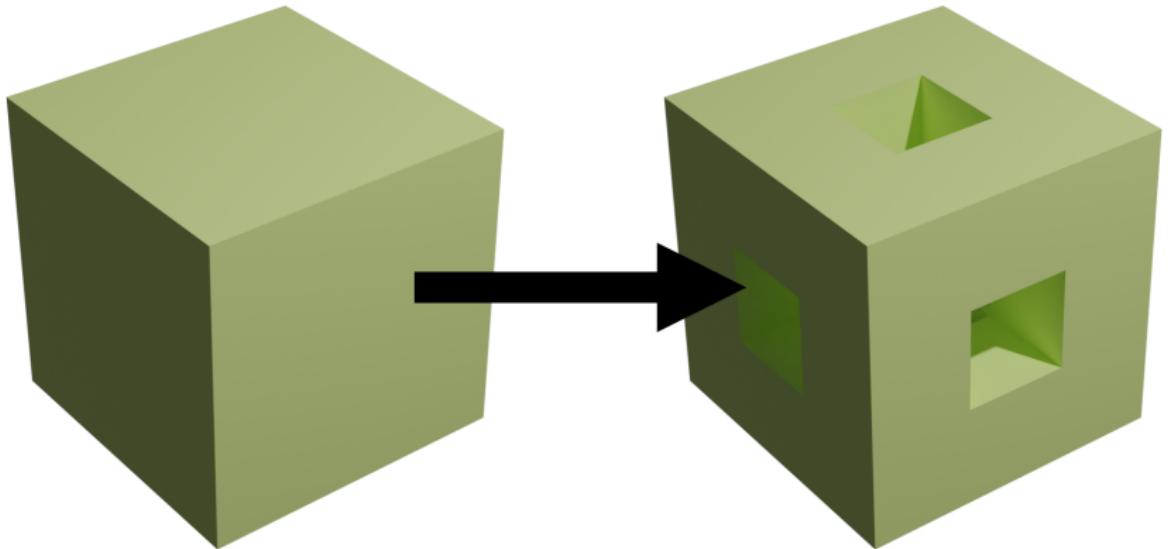
université
PARIS-SACLAY

xlim
INSTITUT
DE MATHÉMATIQUES
Université
de Poitiers





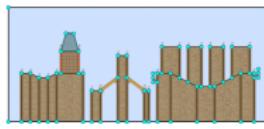




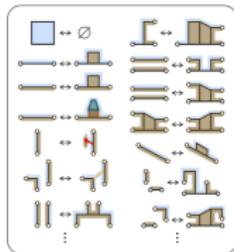
Inferring modeling operations

Inferring the generation of an object:

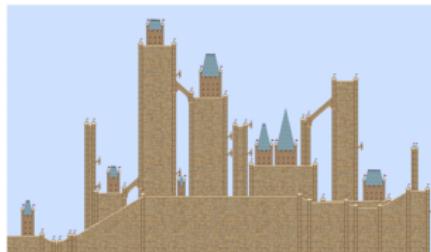
- Inverse procedural modeling: retrieving parameters.¹
- L-systems: retrieving formal rules.²
- Constructive solid geometry: retrieving sequences of operations.³
- Polyhedral decomposition: retrieving a graph grammar. Illustration from (Merrell 2023)



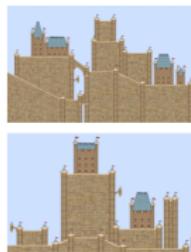
(a) Example Shape



(b) Graph Grammar



(c) Generated Shapes



¹Wu et al. 2014; Emilien et al. 2015.

²Santos et al. 2009; Št'ava et al. 2010; Guo et al. 2020.

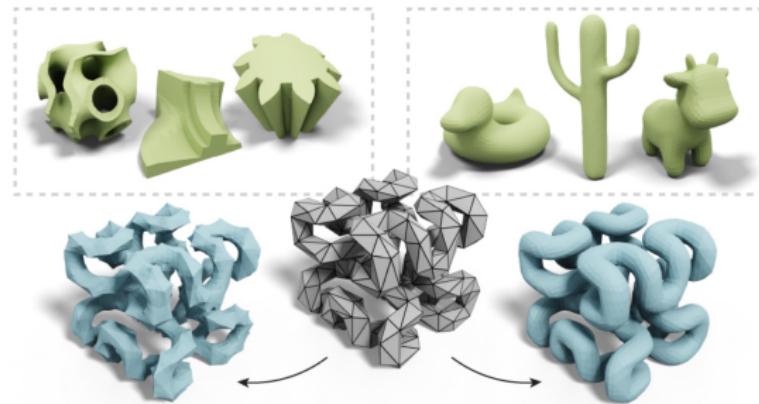
³Sharma et al. 2018; Kania et al. 2020; Xu et al. 2021.

Inferring modeling operations

Inferring the generation of an object

Pure geometry

- Retrieve non-linear weights of a Loop-based subdivision scheme for mesh refinement. Illustration from (Liu et al. 2020).



Program synthesis

How to automatically derive code from a high-level specification of the input-to-output behavior?

Program synthesis

How to automatically derive code from a high-level specification of the input-to-output behavior?

Programming by demonstration

- ① Build a theorem "for all input, there exists an output such that the specification holds."
- ② Construct a proof of the theorem (proof assistant)
- ③ Derive a program from the proof

Program synthesis

How to automatically derive code from a high-level specification of the input-to-output behavior?

Programming by demonstration

Syntax-guided¹

- Search-based approaches that leverage a syntactic template

¹Alur et al. 2013.

Program synthesis

How to automatically derive code from a high-level specification of the input-to-output behavior?

Programming by demonstration

Syntax-guided¹

(Neural approaches, LLM, etc.)

¹Alur et al. 2013.

Example from (Alur et al. 2018)

Consider the specification

$$\forall x \forall y \ (x \leq f(x, y)) \ \wedge \ (y \leq f(x, y)) \ \wedge \ (f(x, y) \in \{x, y\})$$

Example from (Alur et al. 2018)

Consider the specification

$$\forall x \forall y \ (x \leq f(x, y)) \wedge (y \leq f(x, y)) \wedge (f(x, y) \in \{x, y\})$$

Consider the context-free grammar generated by

$$T := x | y | 0 | 1 | T + T | ITE(C, T, T)$$

$$C := (T \leq T) | \neg C | (C \wedge C)$$

Example from (Alur et al. 2018)

Consider the specification

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Consider the context-free grammar generated by

$$\begin{aligned} T &:= x | y | 0 | 1 | T + T | ITE(C, T, T) \\ C &:= (T \leq T) | \neg C | (C \wedge C) \end{aligned}$$

Possible expression

$$f(x, y) = ITE((x \leq y), y, x)$$

Syntax-guided program synthesis

Given

- a function f , specified by a formula φ in a theory T
- a language L of admissible expressions

Find an expression $e \in L$ such that

$$\varphi[f/e] \text{ is valid modulo } T$$

Syntax-guided program synthesis

Given

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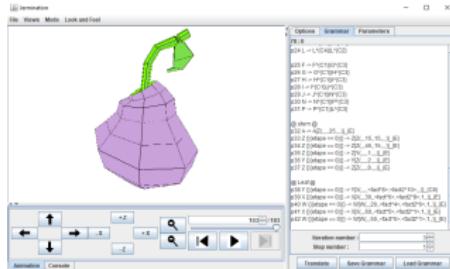
Programming by example¹

- φ derived from an input-output example
- L is a domain-specific language

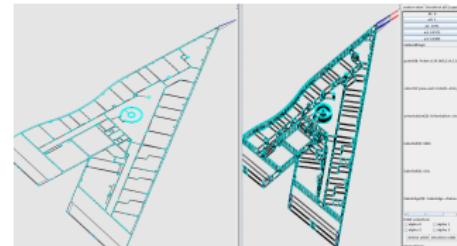
¹Gulwani et al. 2012.



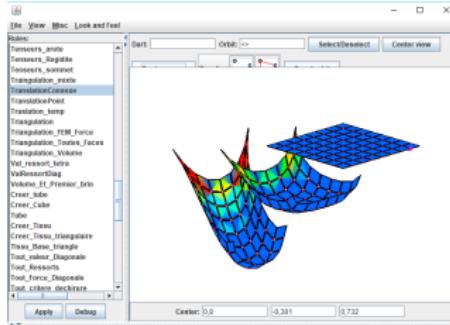
Plant growth



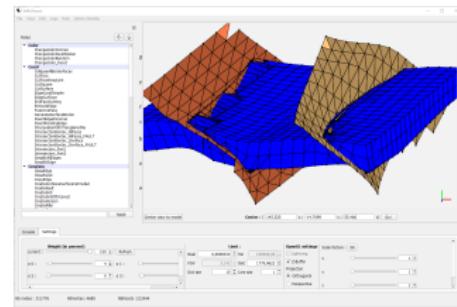
Architecture

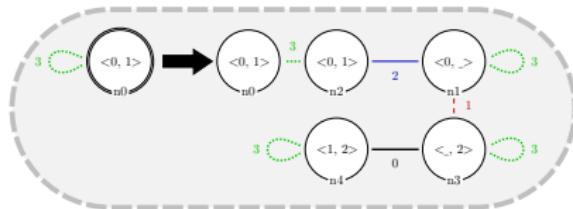
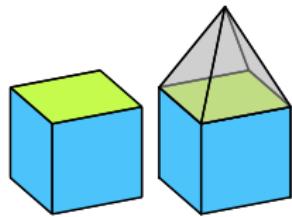


Spring-mass simulations

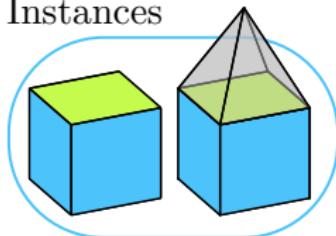


Geology

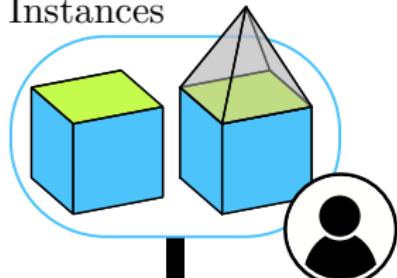




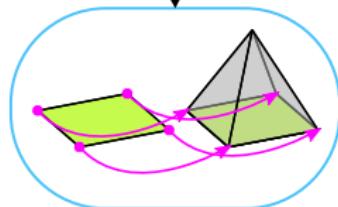
Instances



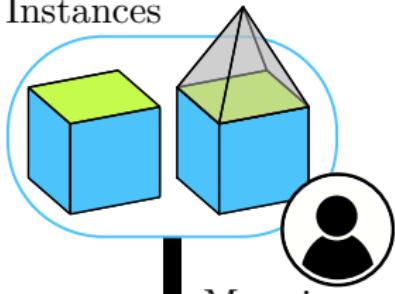
Instances



Mapping



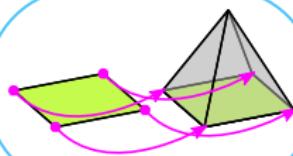
Instances



Mapping

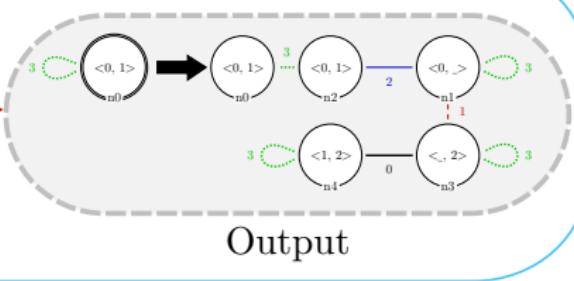


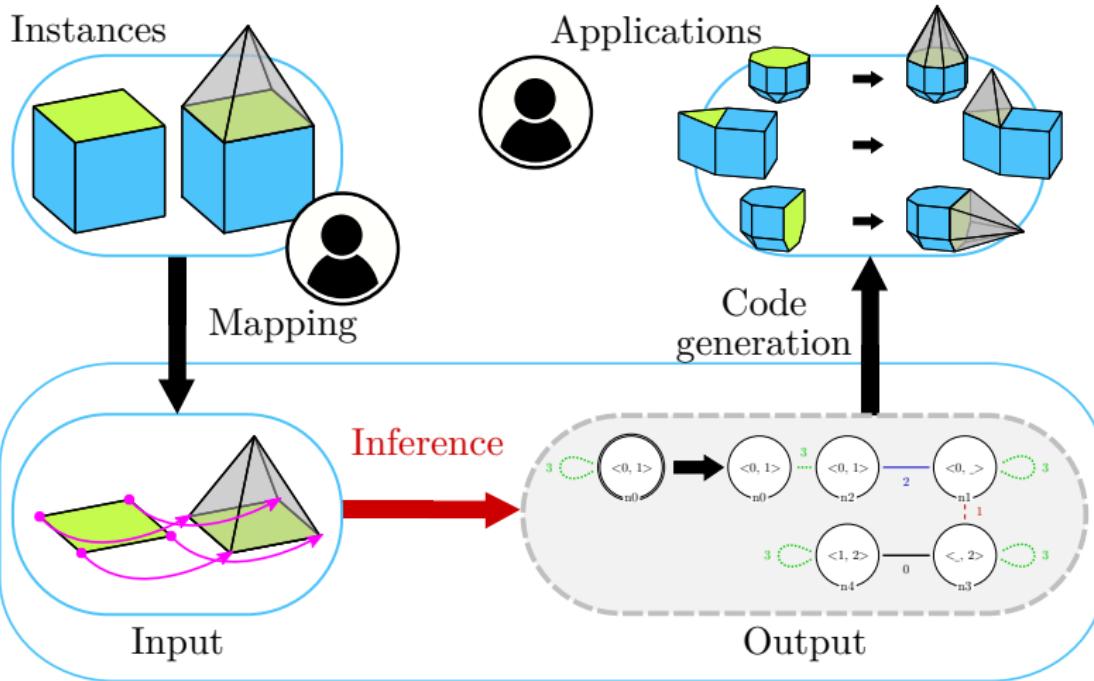
Inference



Input

Output

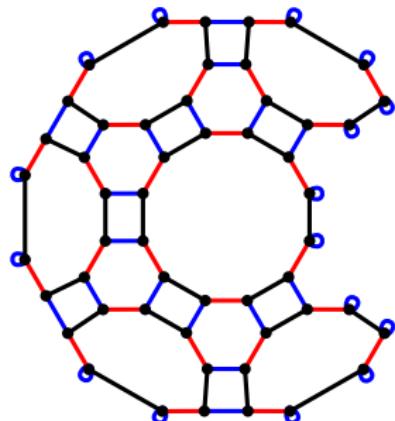




Embedded generalized maps

- ▶ How to represent objects?

Generalized maps¹ (topology)

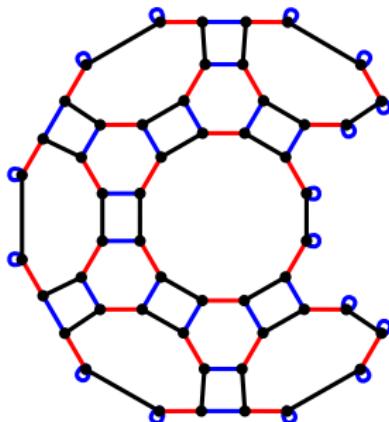


Legend: 0, 1, 2

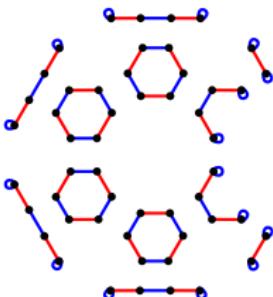
¹Damiand et al. 2014.



Generalized maps¹ (topology)



Orbit: Sub-graph induced by a subset $\langle o \rangle$ of dimensions



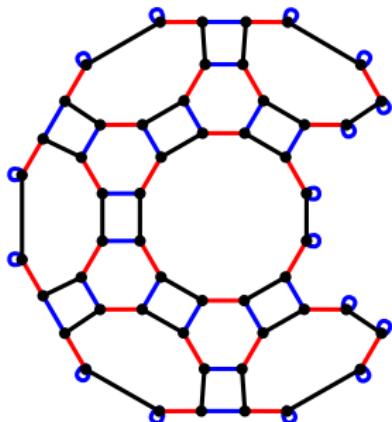
Legend: 0, 1, 2

Vertices: orbits $\langle 1, 2 \rangle$

¹Damiand et al. 2014.



Generalized maps¹ (topology)

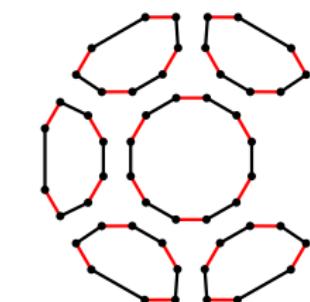


Orbit: Sub-graph induced by a subset $\langle o \rangle$ of dimensions



Legend: 0, 1, 2

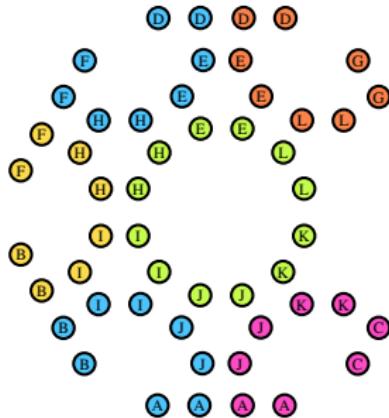
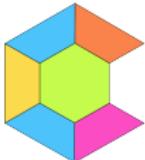
Vertices: orbits $\langle 1, 2 \rangle$



Faces: orbits $\langle 0, 1 \rangle$

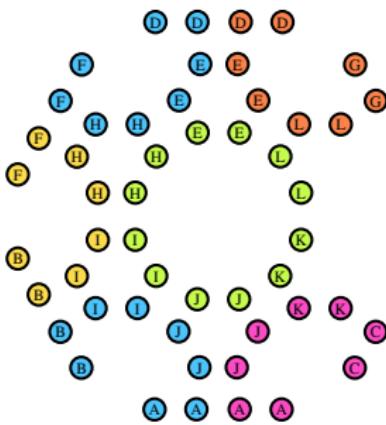
¹Damiand et al. 2014.

Embeddings (geometry)

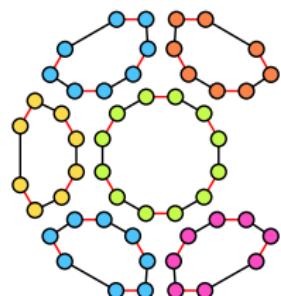
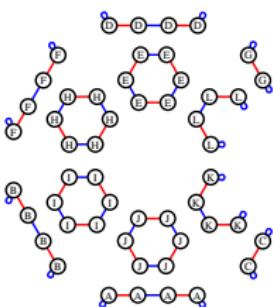


Legend: 0, 1, 2

Embeddings (geometry)



Embedding: function $\pi : \langle o_\pi \rangle \rightarrow \tau_\pi$
with τ_π an abstract data type

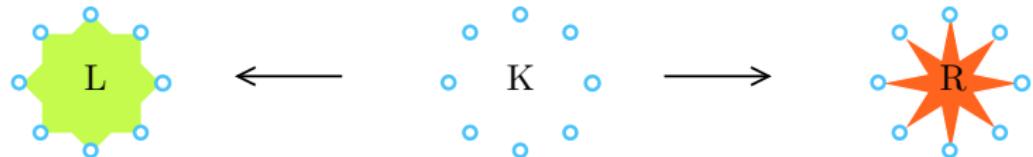


Legend: 0, 1, 2 $position : \langle 1, 2 \rangle \rightarrow \text{Point3}$ $color : \langle 0, 1 \rangle \rightarrow \text{ColorRGB}$

Graph rewriting

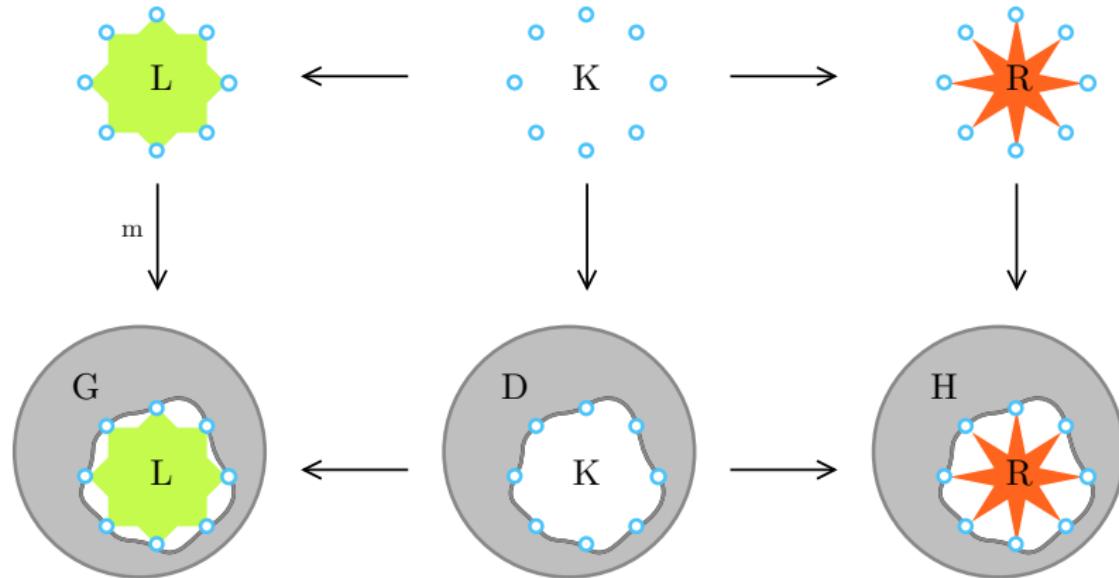
- ▶ How to formalize object transformations?

Graph transformation rules¹



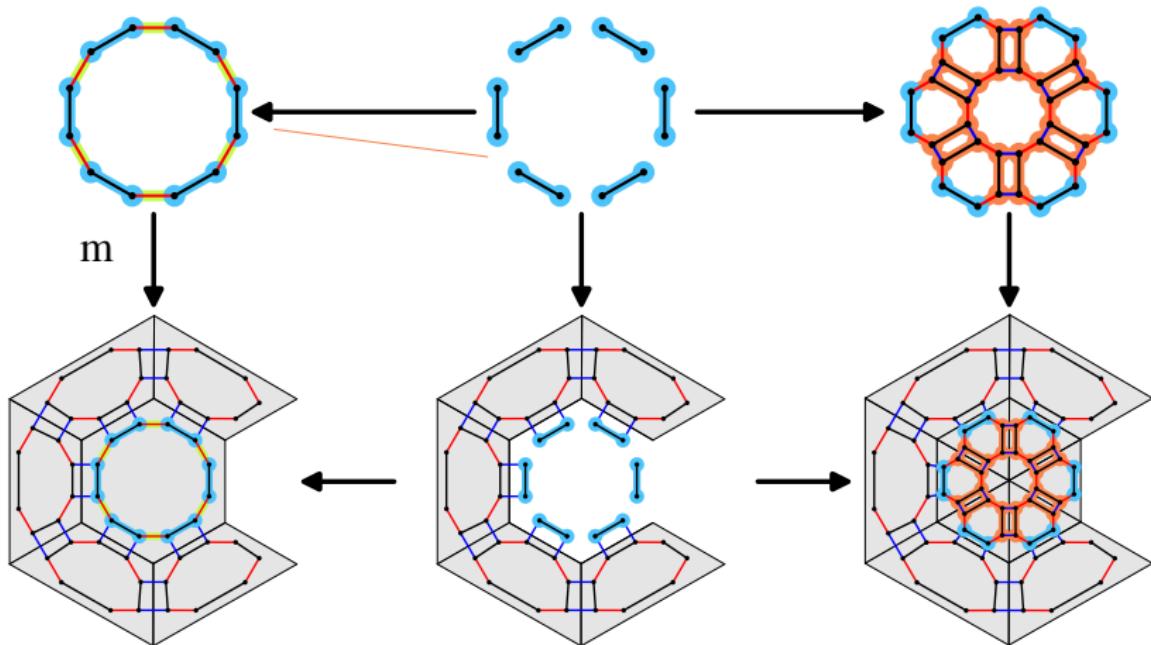
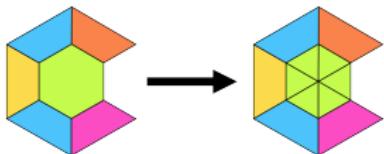
¹Rozenberg 1997; Ehrig et al. 2006; Heckel et al. 2020.

Graph transformation rules¹

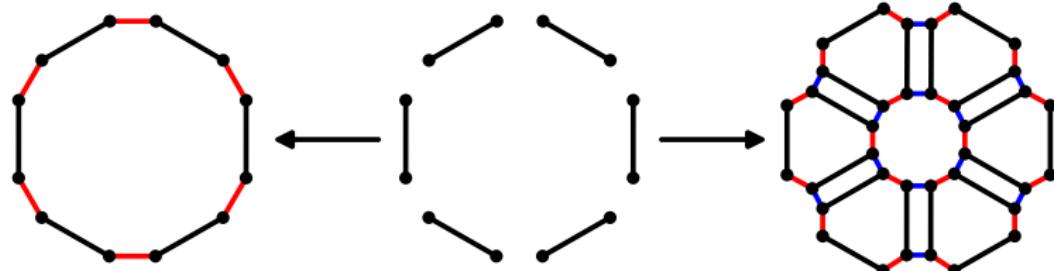
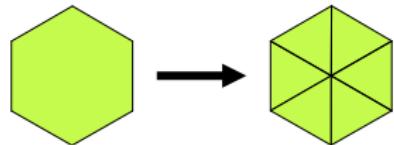


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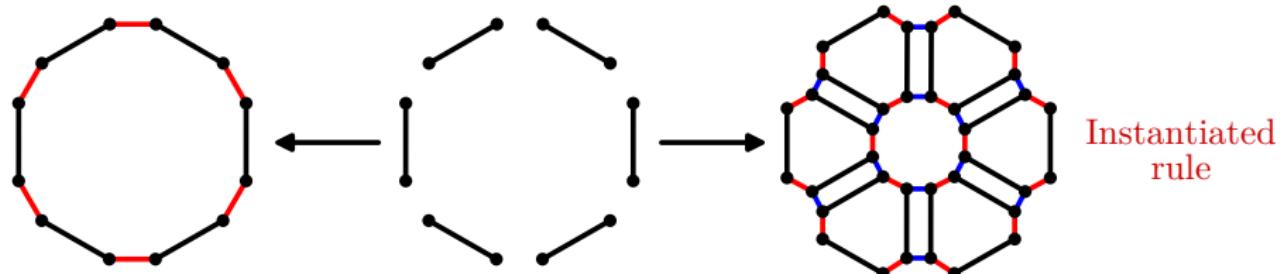
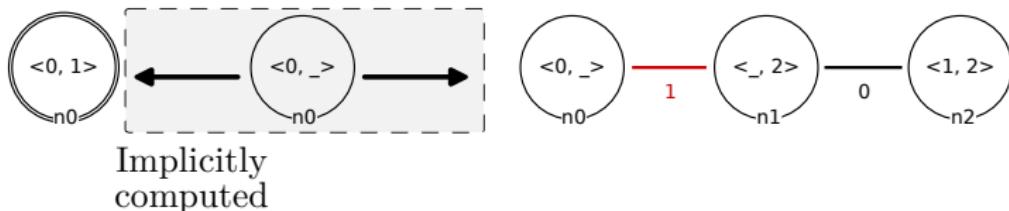
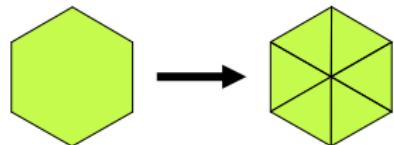
Topological rewriting of Gmaps



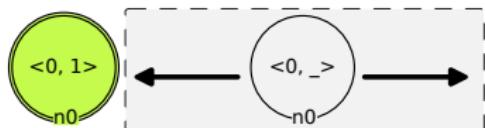
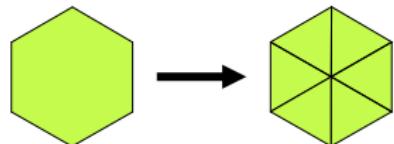
Orbit rewriting



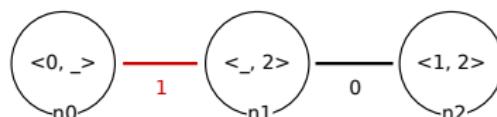
Orbit rewriting



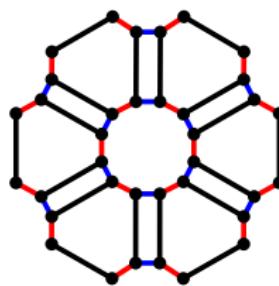
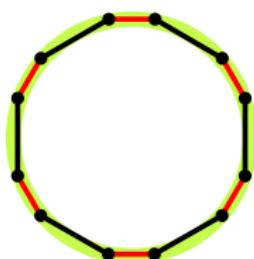
Orbit rewriting



Implicitly
computed

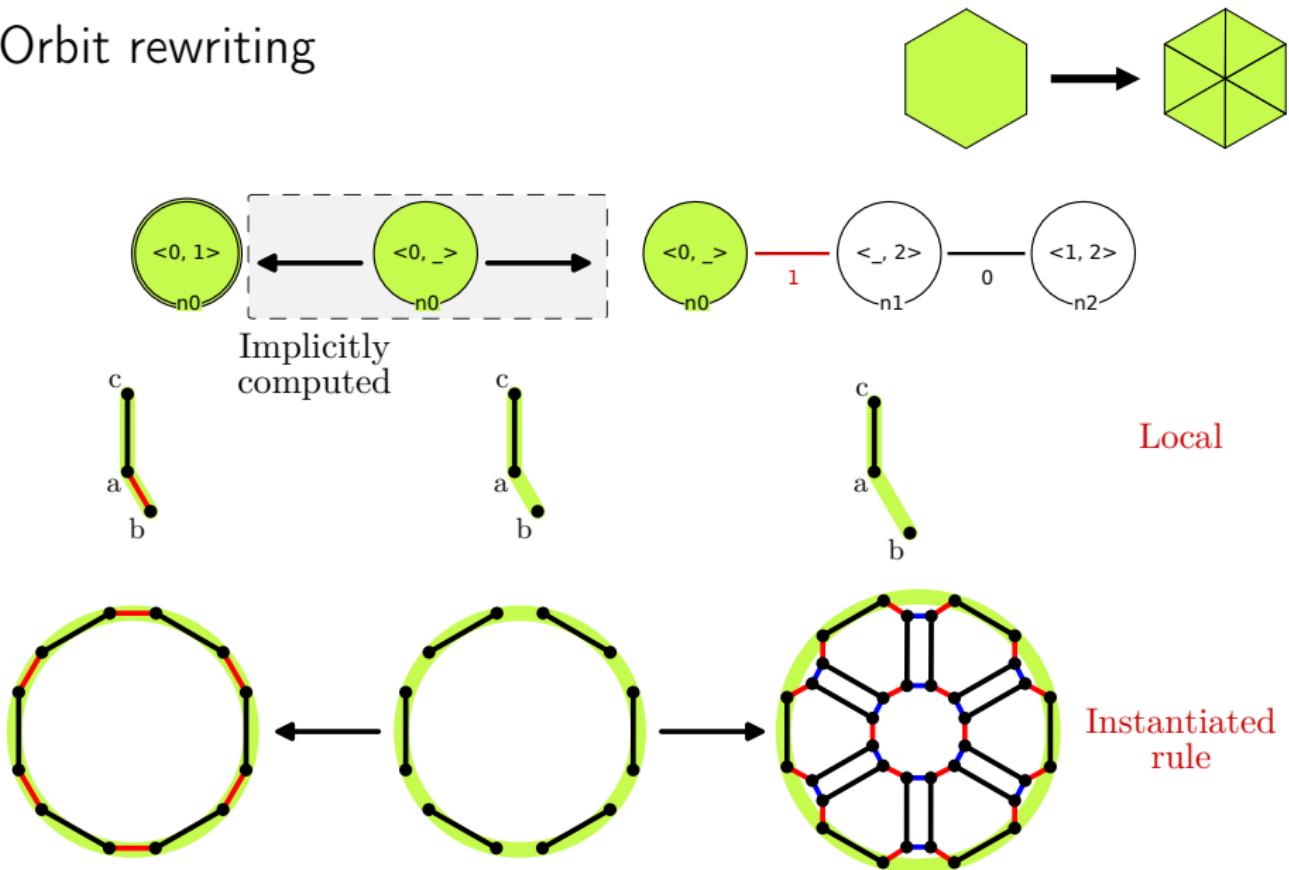


Local

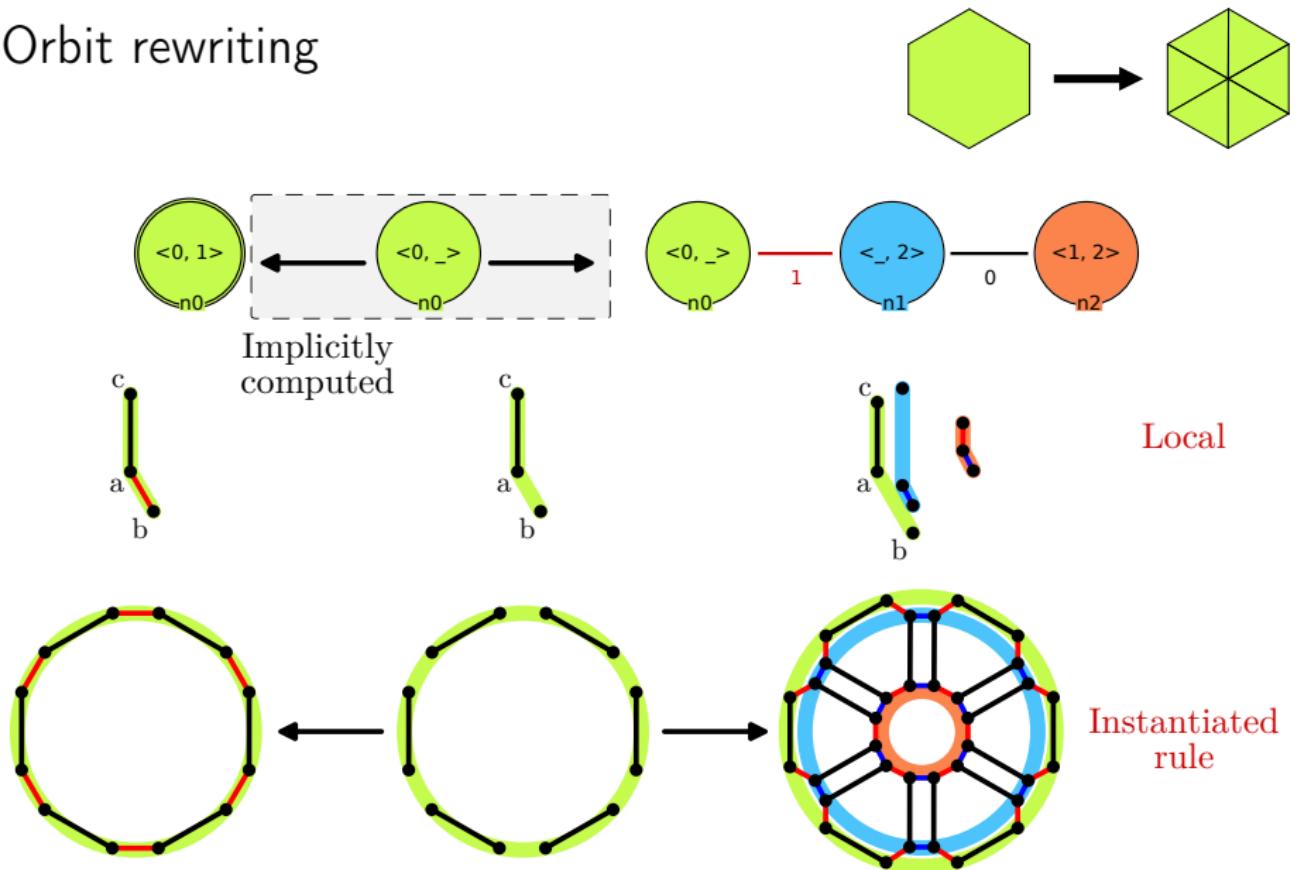


Instantiated
rule

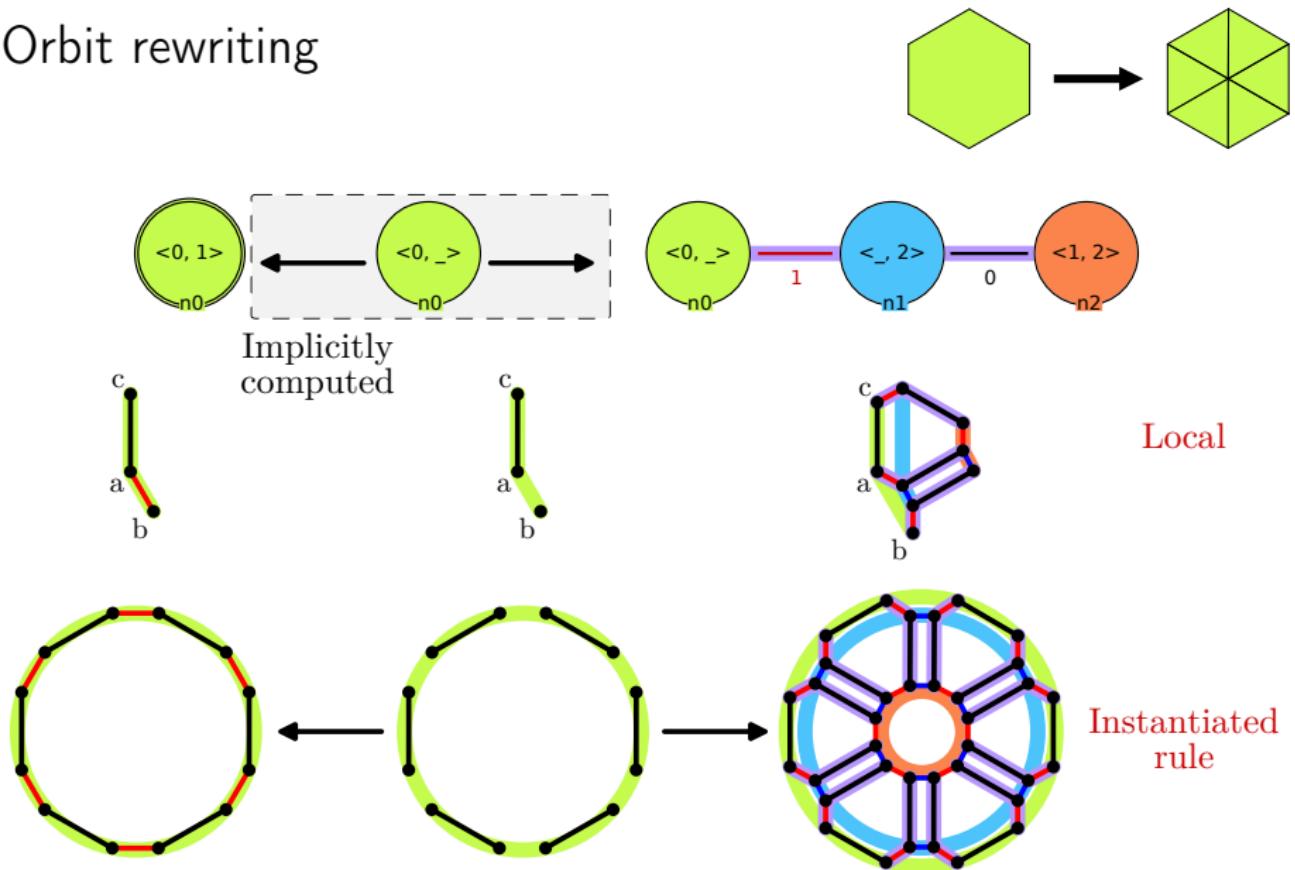
Orbit rewriting



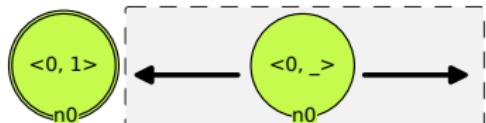
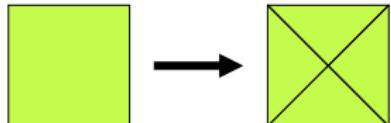
Orbit rewriting



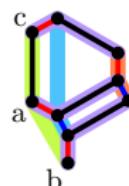
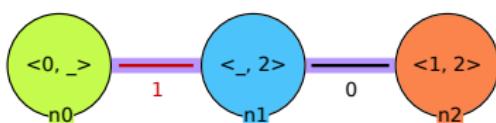
Orbit rewriting



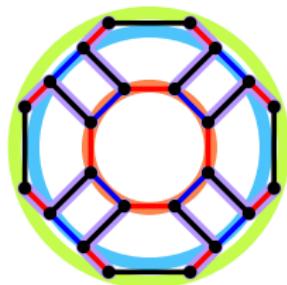
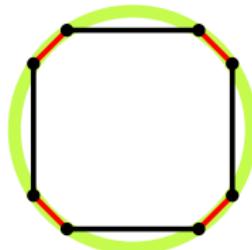
Orbit rewriting



Implicitly
computed

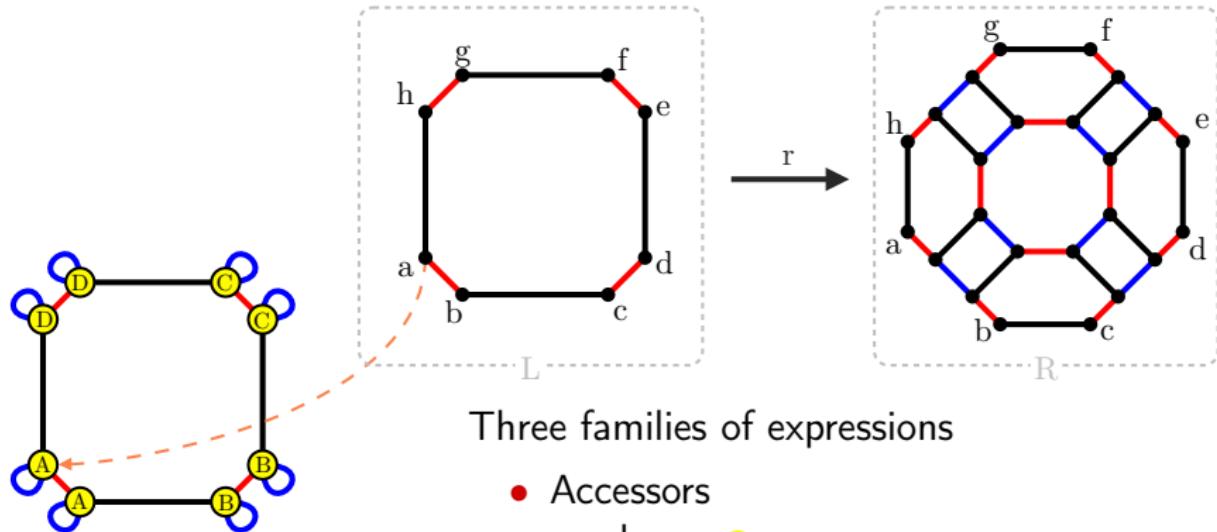


Local



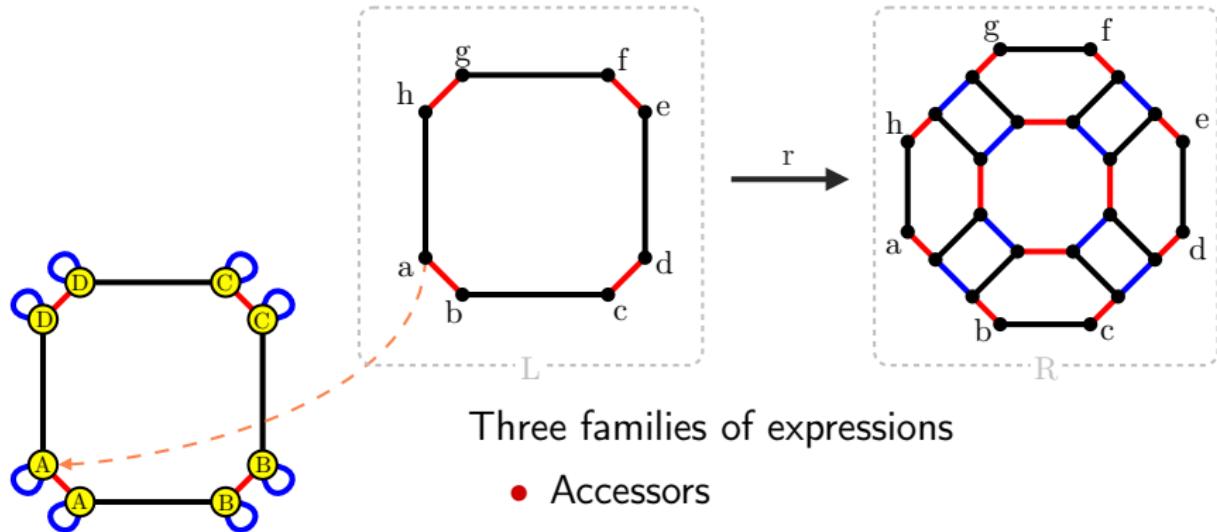
Instantiated
rule

Embedding expressions¹ (towards L)



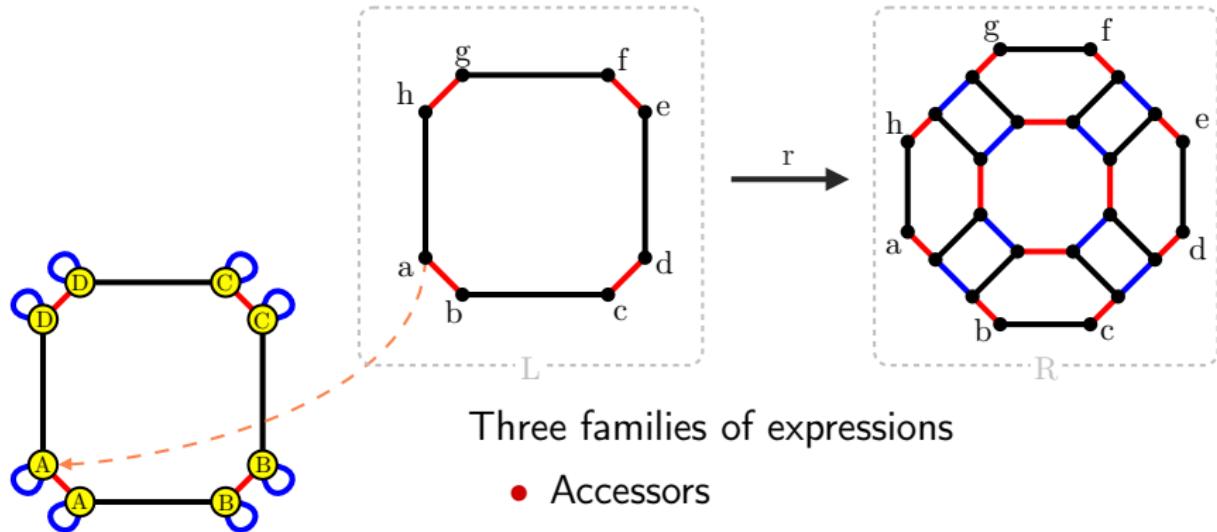
¹Bellet et al. 2017; Arnould et al. 2022.

Embedding expressions¹ (towards L)



¹Bellet et al. 2017; Arnould et al. 2022.

Embedding expressions¹ (towards L)

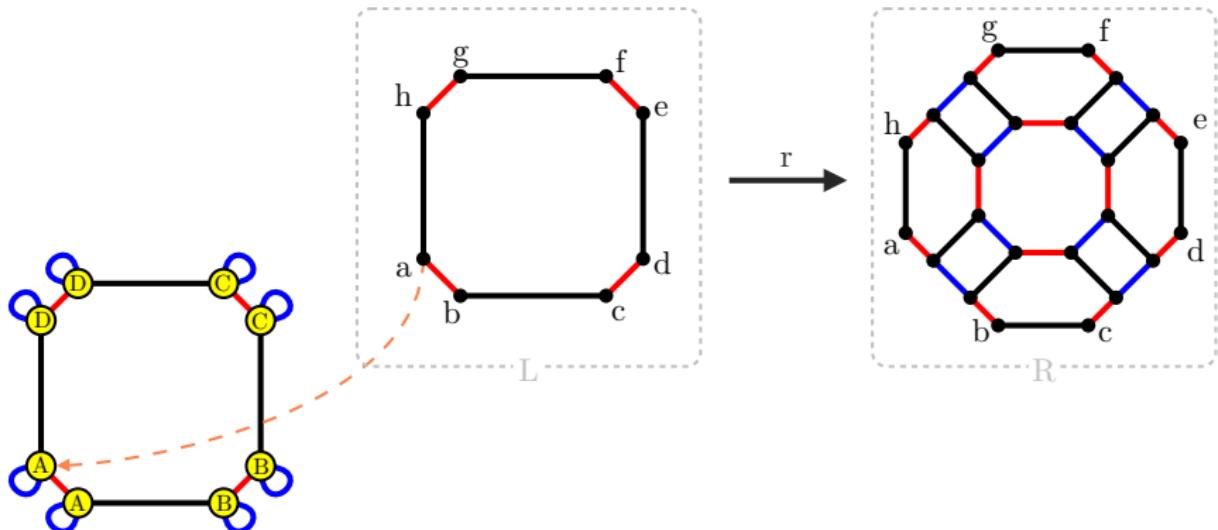
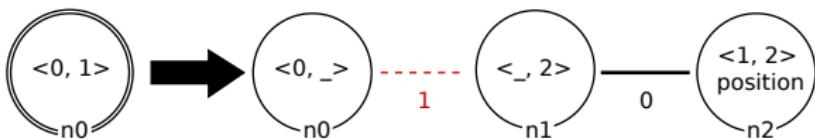


Three families of expressions

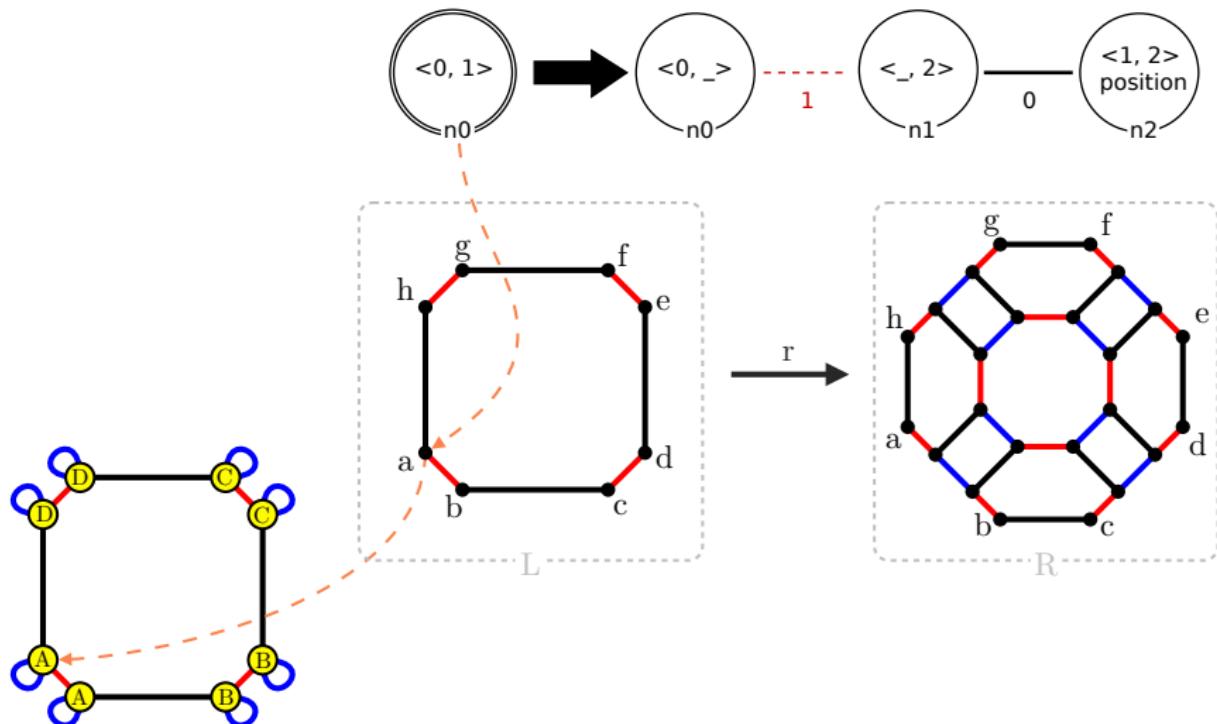
- Accessors
 - Computations
 - Gmap traversals
- $a@0.position = D$
 $\text{position}_{\langle 0,1 \rangle}(a) = \{A, B, C, D\}$

¹Bellet et al. 2017; Arnould et al. 2022.

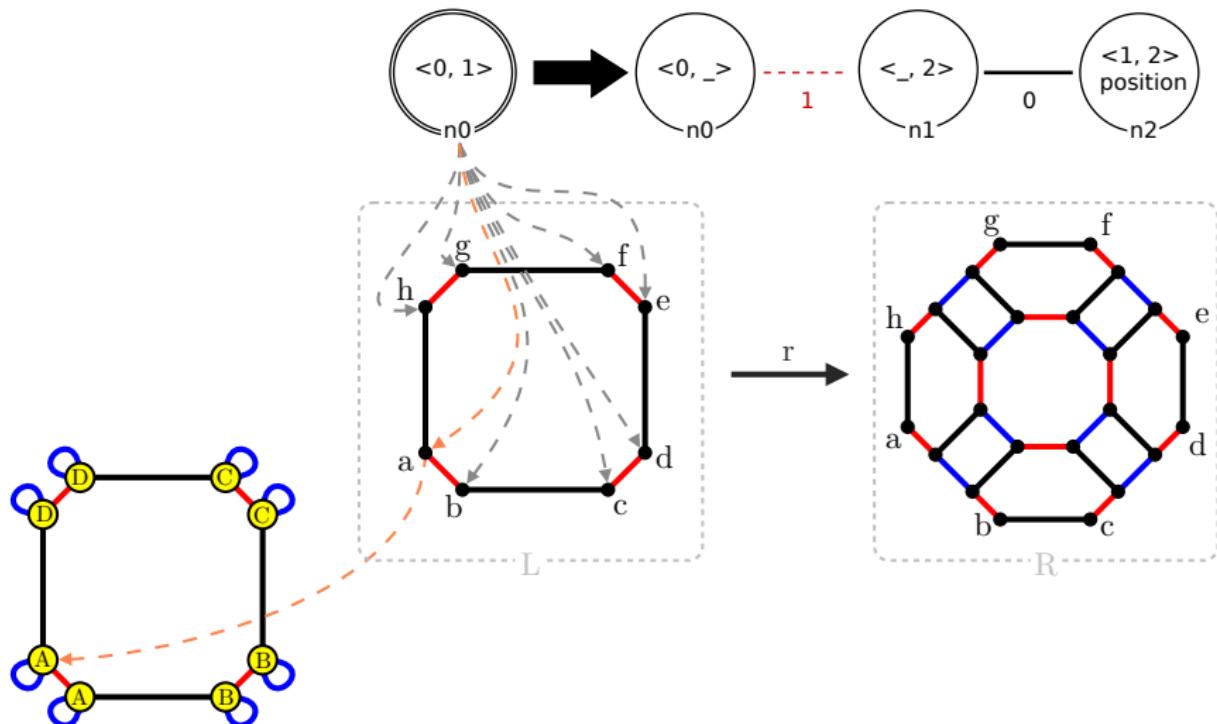
Extension to schemes



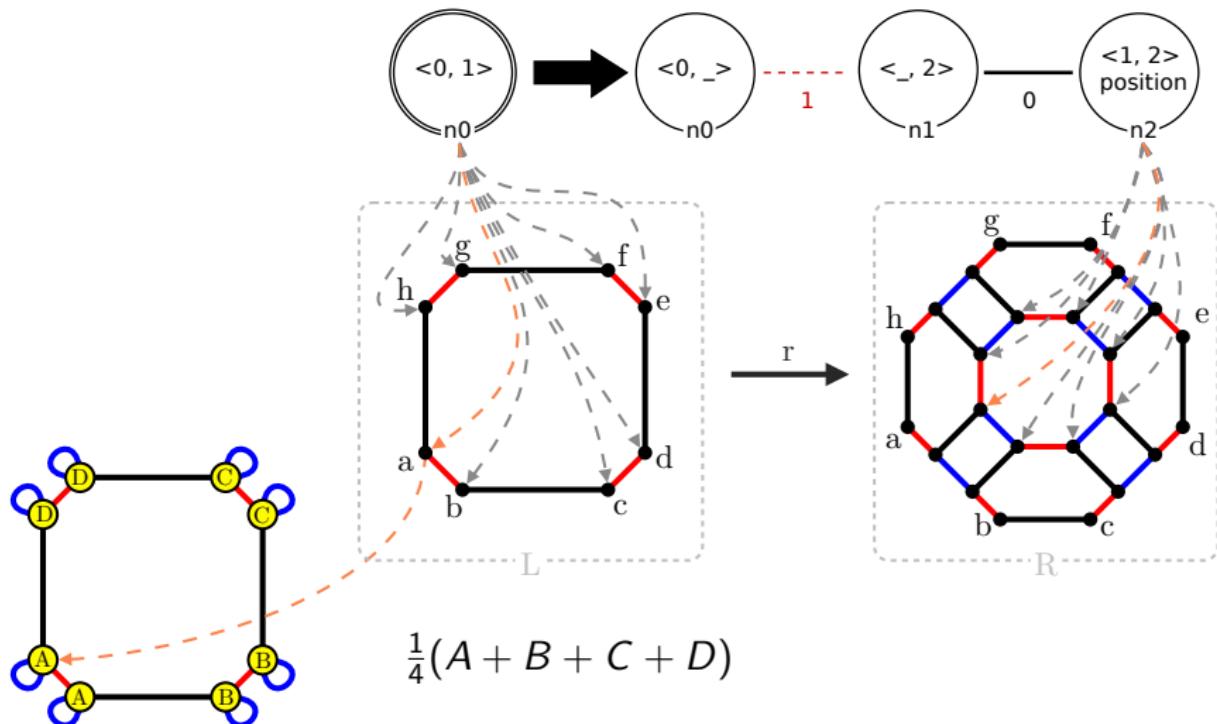
Extension to schemes



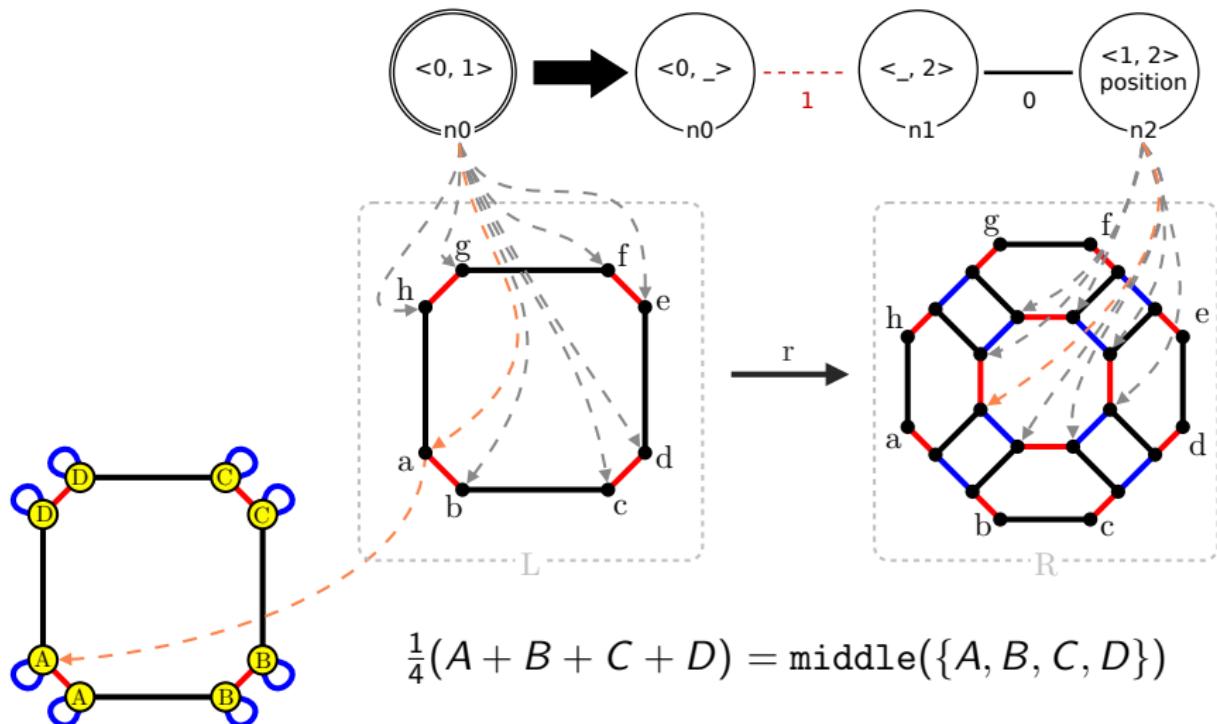
Extension to schemes



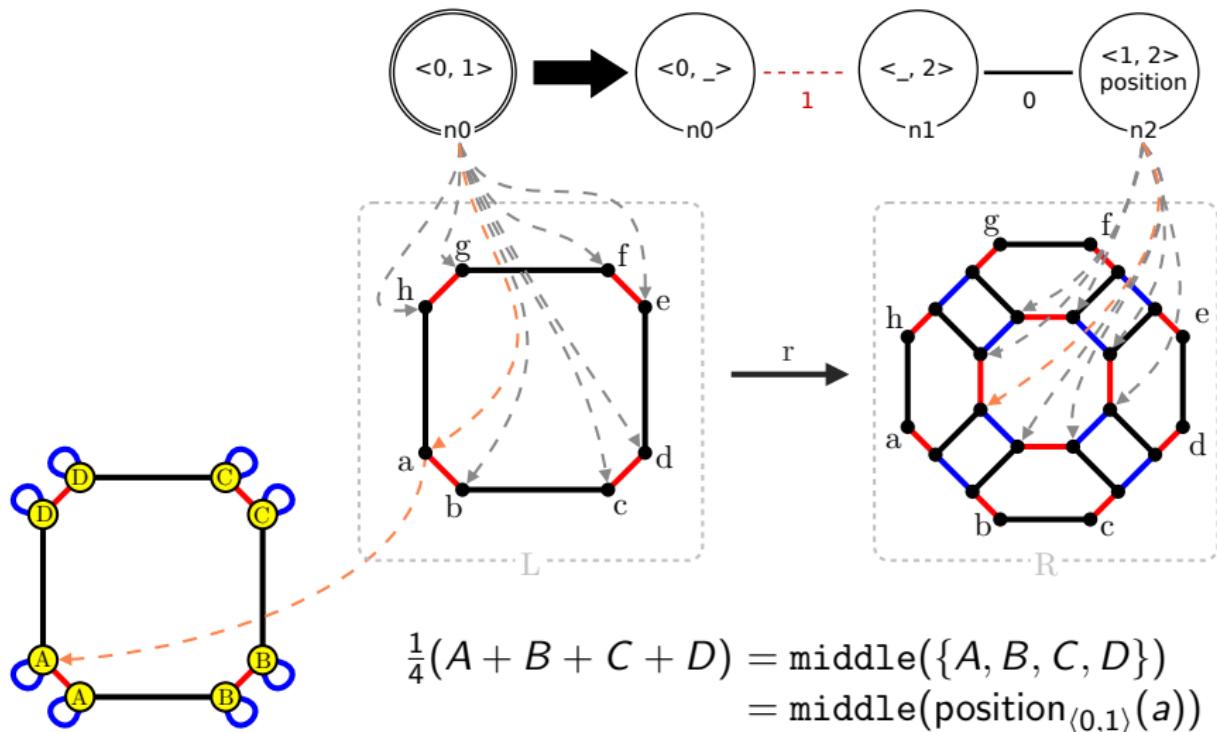
Extension to schemes



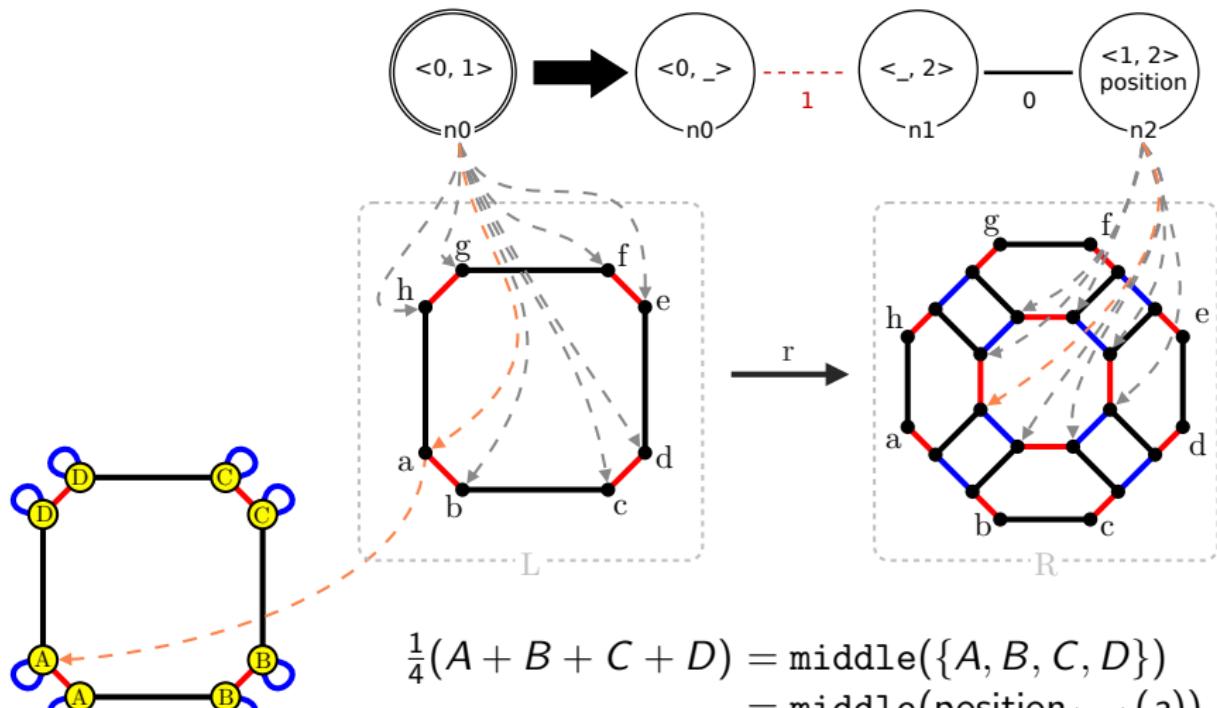
Extension to schemes



Extension to schemes

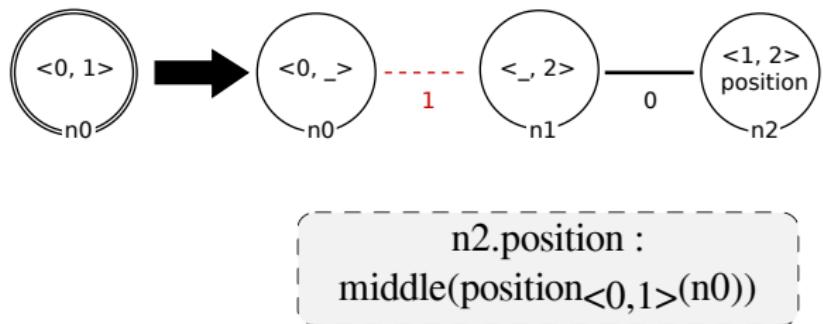


Extension to schemes



$$\begin{aligned} \frac{1}{4}(A + B + C + D) &= \text{middle}(\{A, B, C, D\}) \\ &= \text{middle}(\text{position}_{\langle 0,1 \rangle}(a)) \\ &= \text{middle}(\text{position}_{\langle 0,1 \rangle}(n_0)) \end{aligned}$$

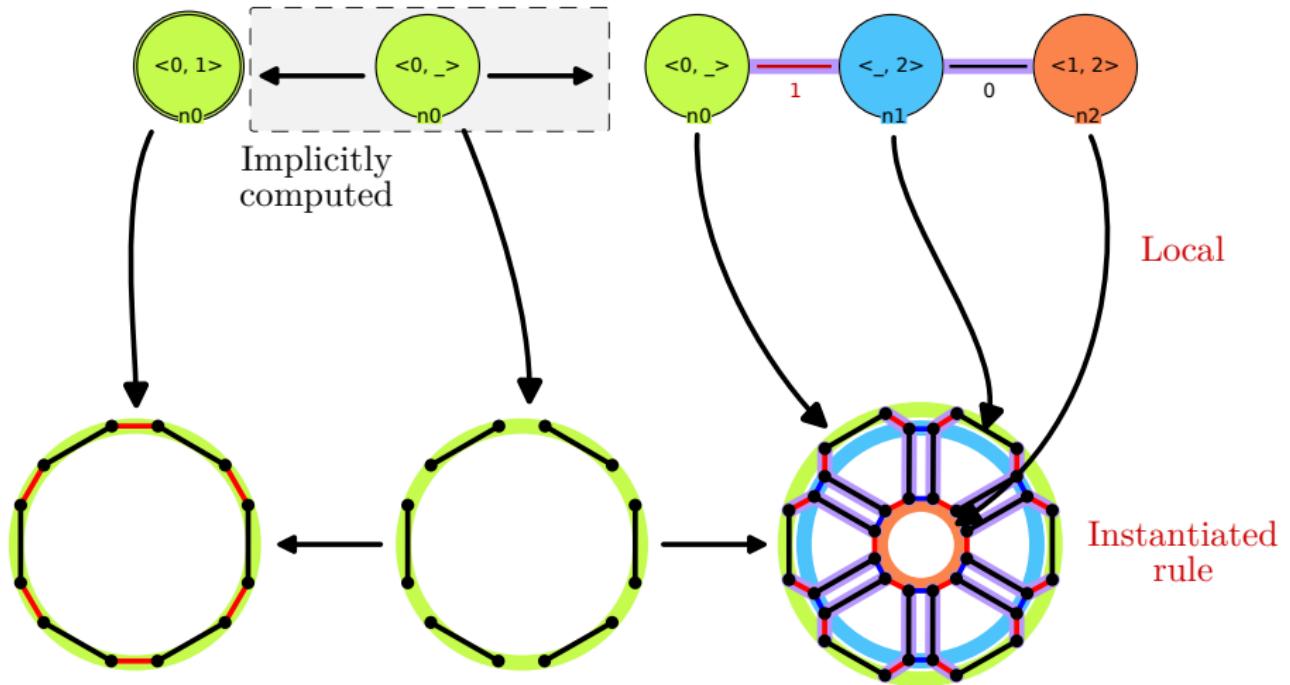
Extension to schemes



Inferring geometric expressions

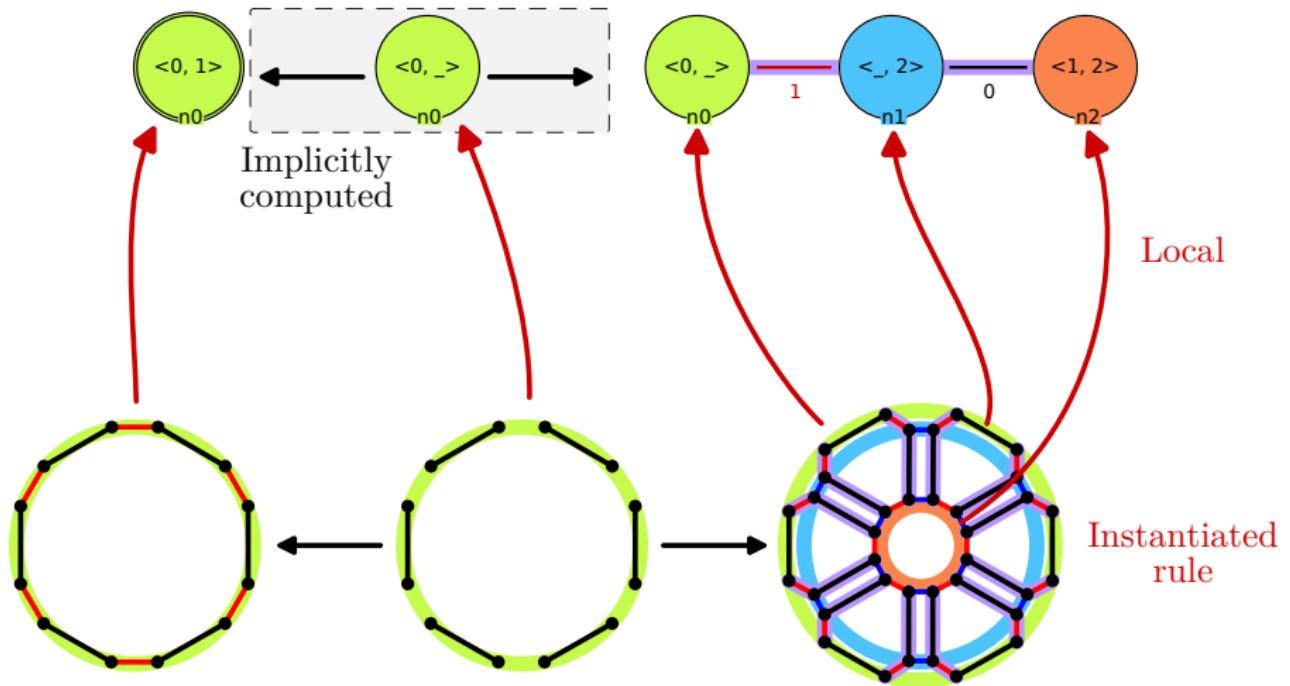
- ▶ How to retrieve the embedding computation expressions?

Topological folding algorithm¹

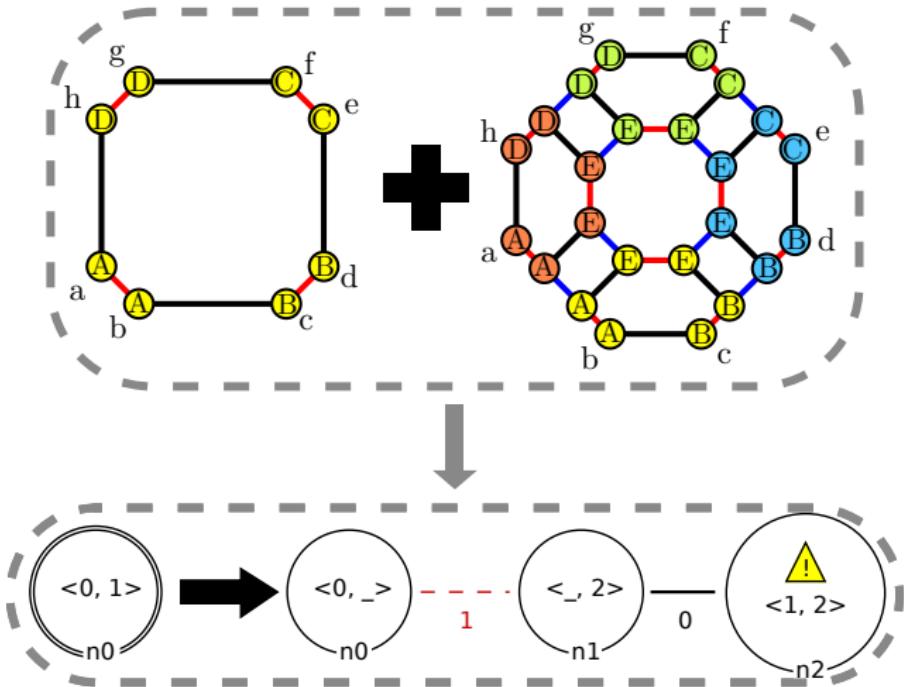


¹Pascual et al. 2022.

Topological folding algorithm¹

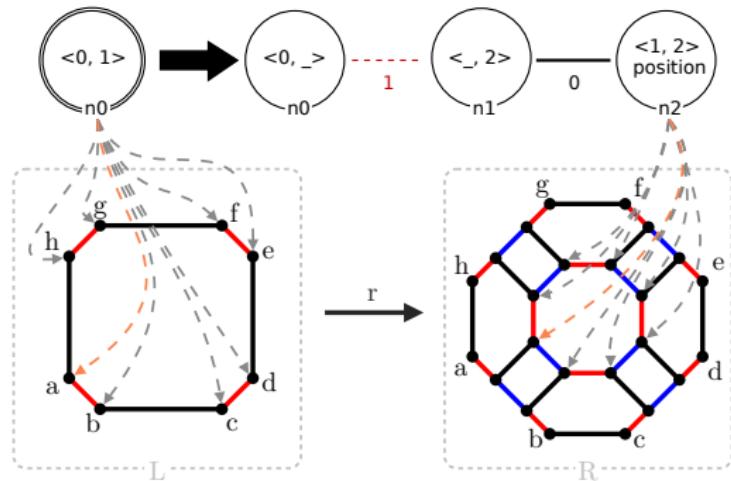


¹Pascual et al. 2022.

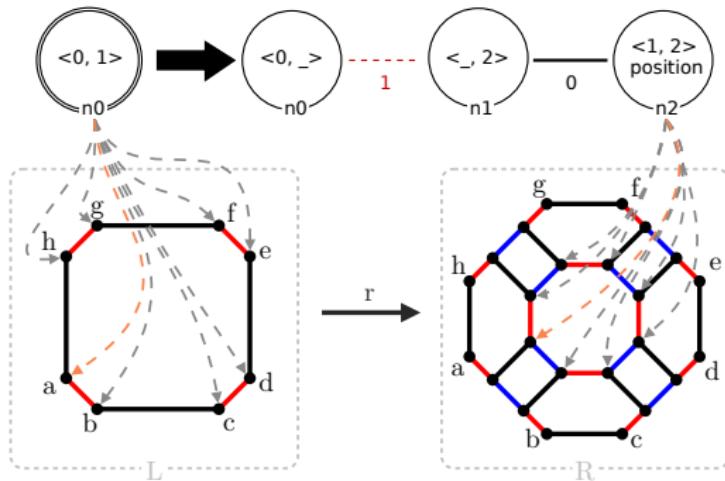


Embedding expressions are missing!

Need for abstraction on schemes

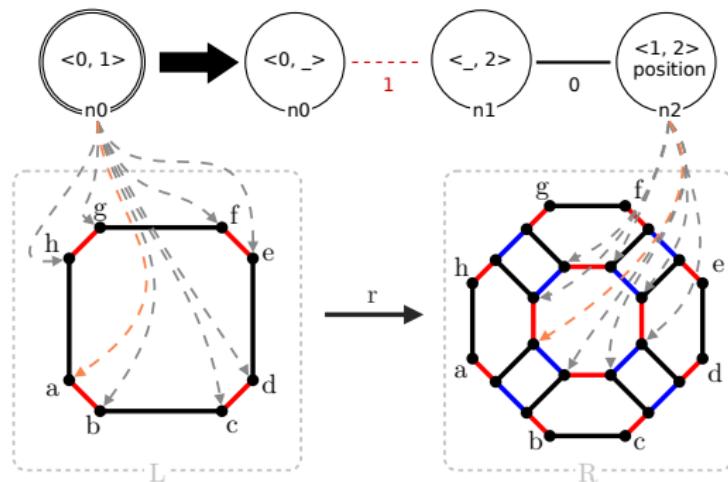


Need for abstraction on schemes



Schemes induce a topological abstraction

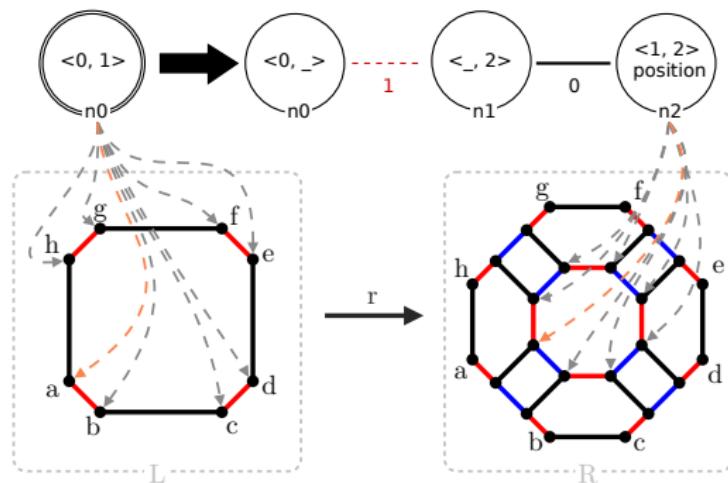
Need for abstraction on schemes



Schemes induce a topological abstraction

Issue: darts in the Gmap share the same expression

Need for abstraction on schemes

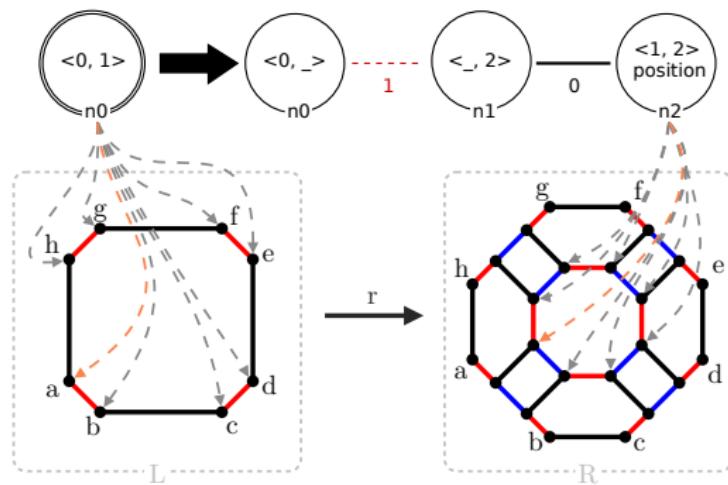


Schemes induce a topological abstraction

Issue: darts in the Gmap share the same expression

Solution: Exploit the topology

Need for abstraction on schemes



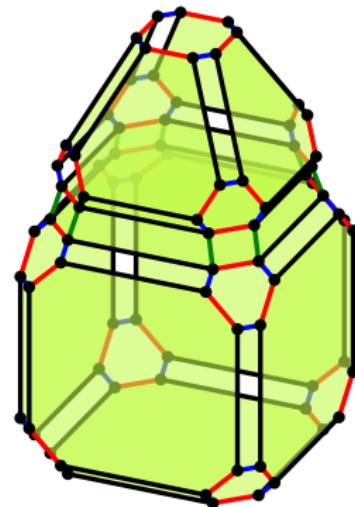
Schemes induce a topological abstraction

Issue: darts in the Gmap share the same expression

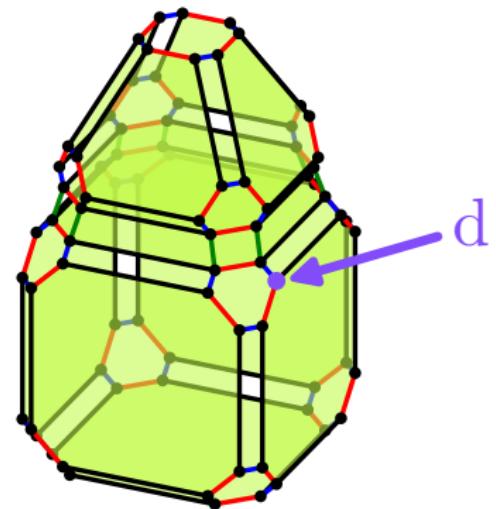
Solution: Exploit the topology

Points of interest

Points of interest



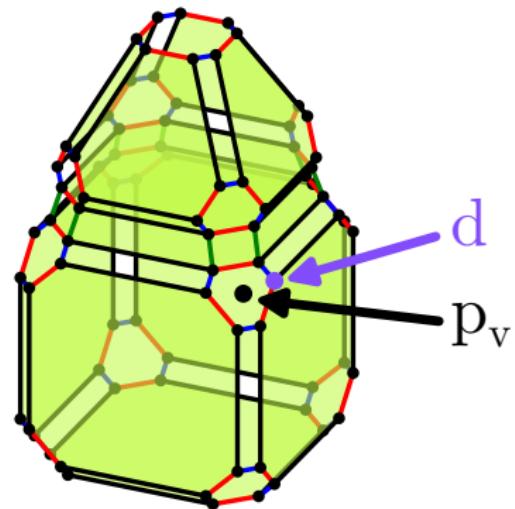
Points of interest



Points of interest

with

- p_v : vertex

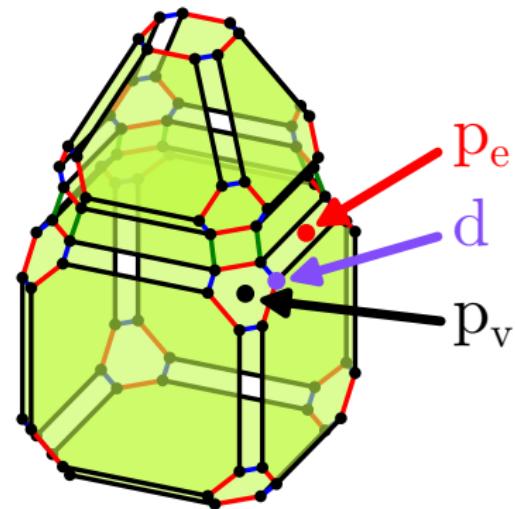


$$p_v = \text{middle}(\text{position}_{\langle\rangle}(d))$$

Points of interest

with

- p_v : vertex
- p_e : edge midpoint

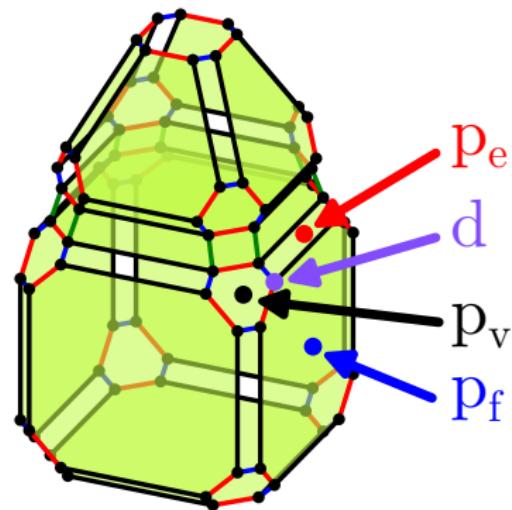


$$p_e = \text{middle}(\text{position}_{\langle 0 \rangle}(d))$$

Points of interest

with

- p_v : vertex
- p_e : edge midpoint
- p_f : face barycenter

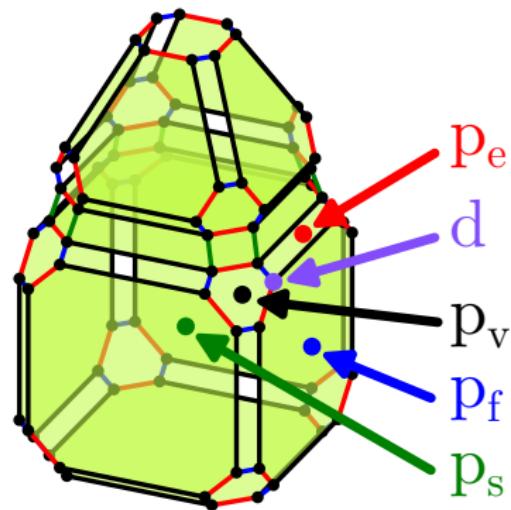


$$p_f = \text{middle}(\text{position}_{\langle 0,1 \rangle}(d))$$

Points of interest

with

- p_v : vertex
- p_e : edge midpoint
- p_f : face barycenter
- p_s : volume barycenter

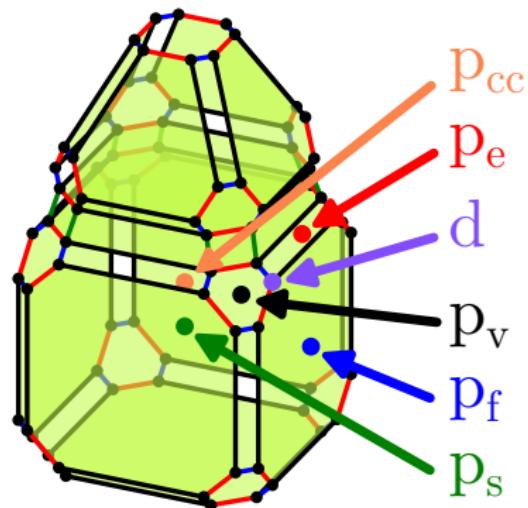


$$p_s = \text{middle}(\text{position}_{\langle 0,1,2 \rangle}(d))$$

Points of interest

with

- p_v : vertex
- p_e : edge midpoint
- p_f : face barycenter
- p_s : volume barycenter
- p_{cc} : CC barycenter



$$p_{cc} = \text{middle}(\text{position}_{\langle 0,1,2,3 \rangle}(d))$$

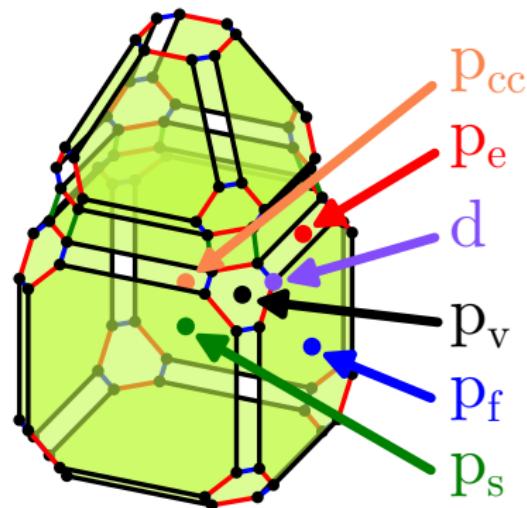
Points of interest

with

- p_v : vertex
- p_e : edge midpoint
- p_f : face barycenter
- p_s : volume barycenter
- p_{cc} : CC barycenter

Looking for

$$f(p_v, p_e, p_f, p_s, p_{cc})$$



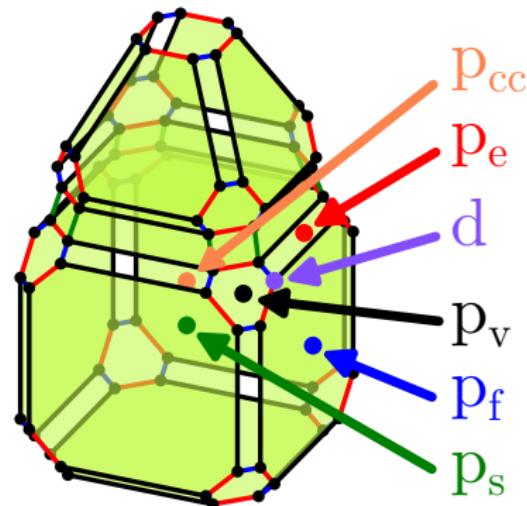
Points of interest

with

- p_v : vertex
- p_e : edge midpoint
- p_f : face barycenter
- p_s : volume barycenter
- p_{cc} : CC barycenter

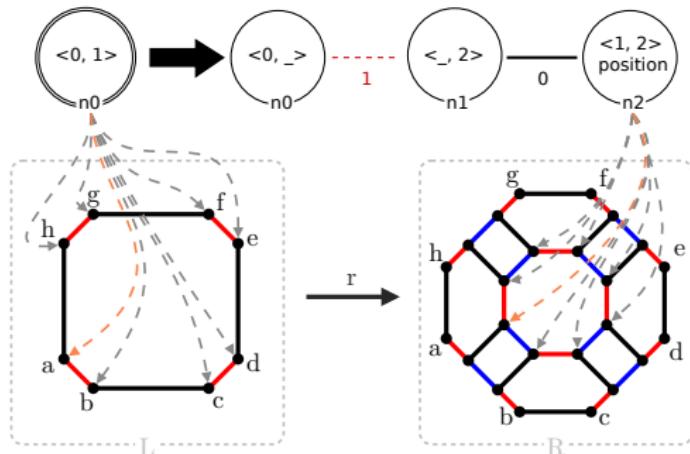
Looking for

$$f(p_v, p_e, p_f, p_s, p_{cc}) = w_v p_v + w_e p_e + w_f p_f + w_s p_s + w_{cc} p_{cc} + t$$



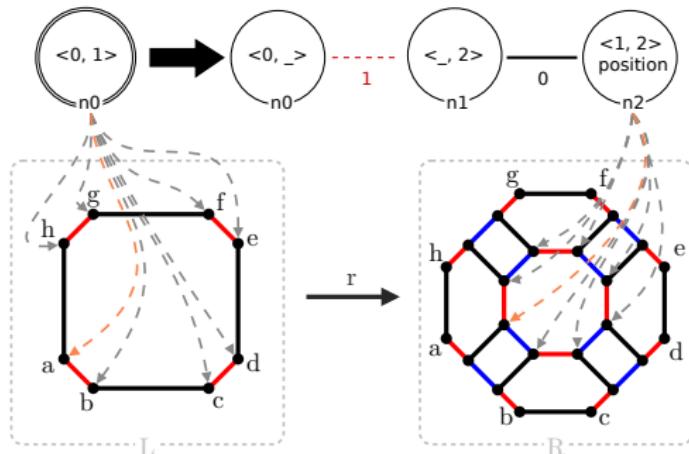
L is the set of affine expressions over the points of interest

Building the logical specification



The position expression of n_2 only depends on n_0

Building the logical specification

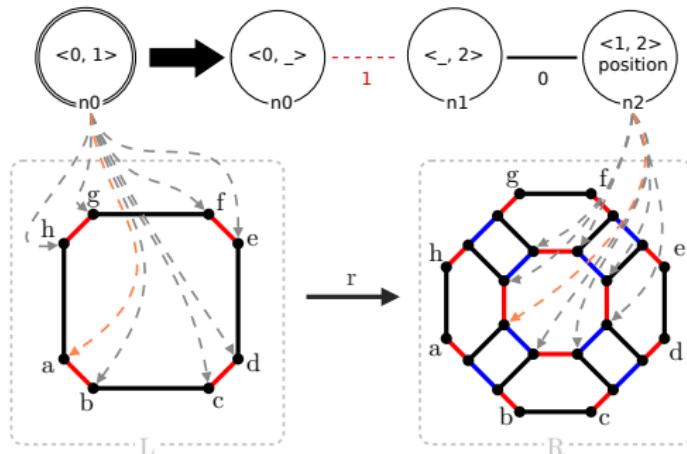


The position expression of n_2 only depends on n_0

Symbolic equation

$$n_2.\text{position} = w_v n_0.p_v + w_e n_0.p_e + w_f n_0.p_f + w_s n_0.p_s + w_{cc} n_0.p_{cc} + t$$

Building the logical specification



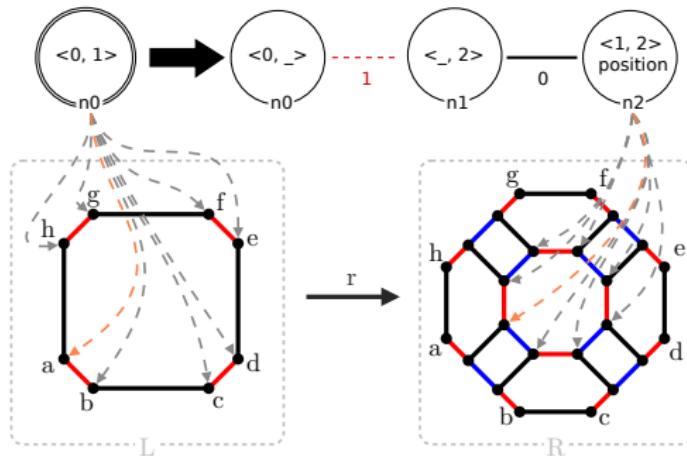
The position expression of *n2* only depends on *n0*

- One equation per dart (8 darts).

Symbolic equation

$$n2.\text{position} = w_v n0.p_v + w_e n0.p_e + w_f n0.p_f + w_s n0.p_s + w_{cc} n0.p_{cc} + t$$

Building the logical specification



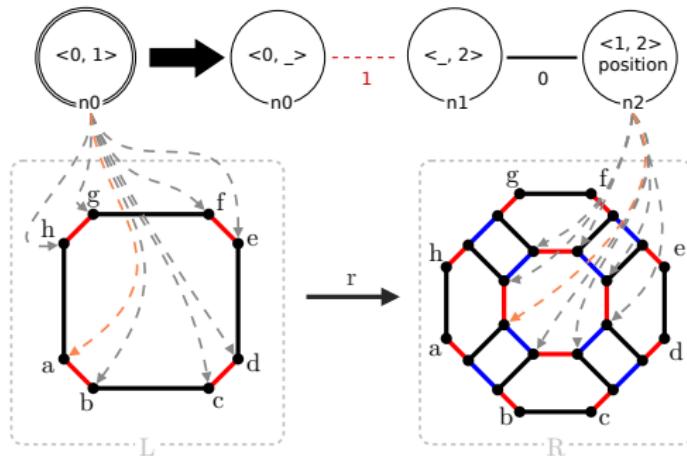
The position expression of *n2* only depends on *n0*

- One equation per dart (8 darts).
- Split per coordinate (on *x*, *y*, *z*).

Symbolic equation

$$n2.\text{position} = w_v n0.p_v + w_e n0.p_e + w_f n0.p_f + w_s n0.p_s + w_{cc} n0.p_{cc} + t$$

Building the logical specification



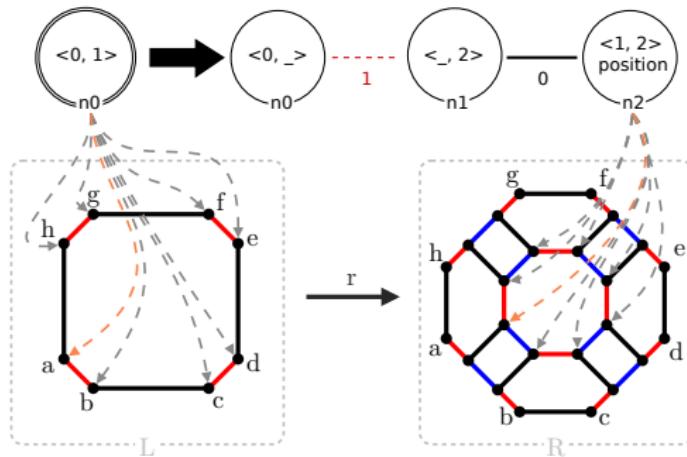
The position expression of $n2$ only depends on $n0$

- One equation per dart (8 darts).
- Split per coordinate (on x, y, z).
- 24 equations and 8 variables.

Symbolic equation

$$n2.\text{position} = w_v n0.p_v + w_e n0.p_e + w_f n0.p_f + w_s n0.p_s + w_{cc} n0.p_{cc} + t$$

Building the logical specification

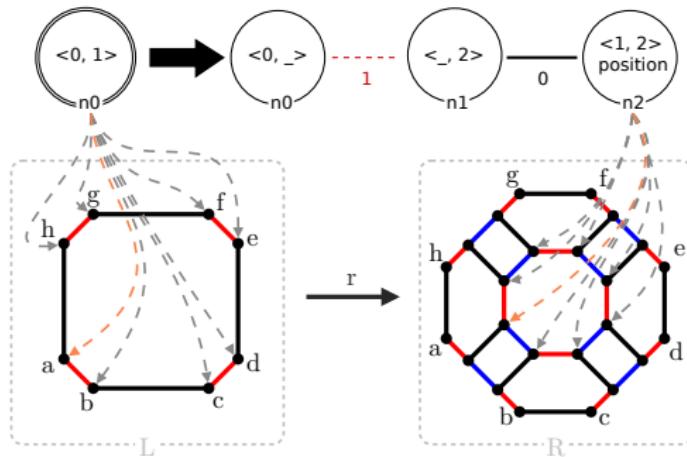


The position expression of n_2 only depends on n_0

- One equation per dart (8 darts).
- Split per coordinate (on x, y, z).
- 24 equations and 8 variables.

φ is the concrete system induced by the input-output example

Building the logical specification



The position expression of n_2 only depends on n_0

- One equation per dart (8 darts).
- Split per coordinate (on x, y, z).
- 24 equations and 8 variables.

φ is the concrete system induced by the input-output example

Solved via an SMT solver (Z3, OR-Tools)

Solving the barycentric triangulation

Symbolic equation

$$n2.\text{position} = w_v n0.p_v + w_e n0.p_e + w_f n0.p_f + w_s n0.p_s + w_{cc} n0.p_{cc} + t$$

Solving the barycentric triangulation

Symbolic equation

$$n2.position = w_v n0.p_v + w_e n0.p_e + w_f n0.p_f + w_s n0.p_s + w_{cc} n0.p_{cc} + t$$

Generated system

$$\begin{cases} (0.5; 0.5) = w_v * (0; 0) + w_e * (0.5; 0) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ (0.5; 0.5) = w_v * (1; 0) + w_e * (0.5; 0) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ (0.5; 0.5) = w_v * (1; 0) + w_e * (1; 0.5) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ (0.5; 0.5) = w_v * (1; 1) + w_e * (1; 0.5) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \end{cases}$$

Solving the barycentric triangulation

Symbolic equation

$$n2.position = w_v n0.p_v + w_e n0.p_e + w_f n0.p_f + w_s n0.p_s + w_{cc} n0.p_{cc} + t$$

Generated system

$$\begin{cases} (0.5; 0.5) = w_v * (0; 0) + w_e * (0.5; 0) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ (0.5; 0.5) = w_v * (1; 0) + w_e * (0.5; 0) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ (0.5; 0.5) = w_v * (1; 0) + w_e * (1; 0.5) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ (0.5; 0.5) = w_v * (1; 1) + w_e * (1; 0.5) + w_f * (0.5; 0.5) + w_s * (0.5; 0.5) + w_{cc} * (0.5; 0.5) + (tx; ty) \\ \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \quad \vdots \end{cases}$$

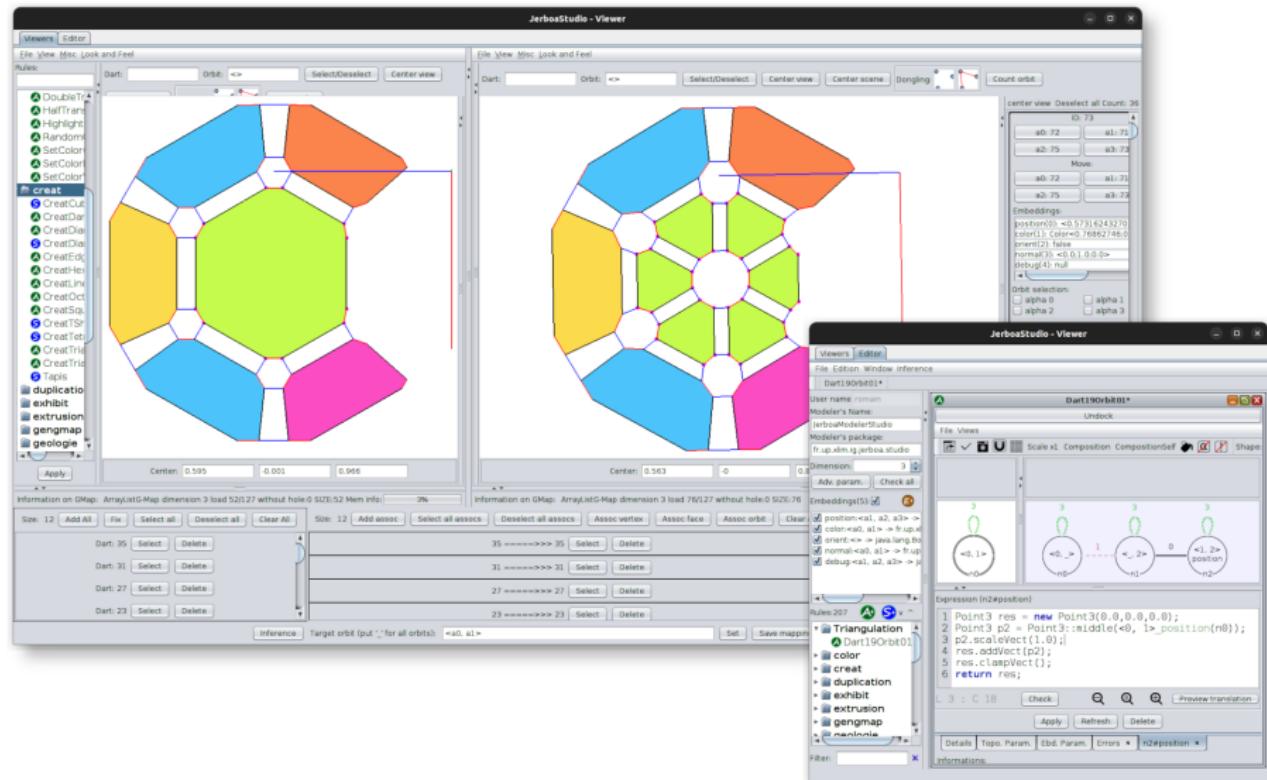
Solution found

- $w_v = 0.0$
- $w_e = 0.0$
- $w_f = 1.0$
- $w_{cc} = 0.0$
- $t = (0.0, 0.0)$

JerboaStudio and applications

- ▶ Implementation in Jerboa

JerboaStudio



5. JerboaStudio and applications

Generated code for the triangulation



```
// no translation
Point3 res = new Point3(0.0,0.0,0.0);

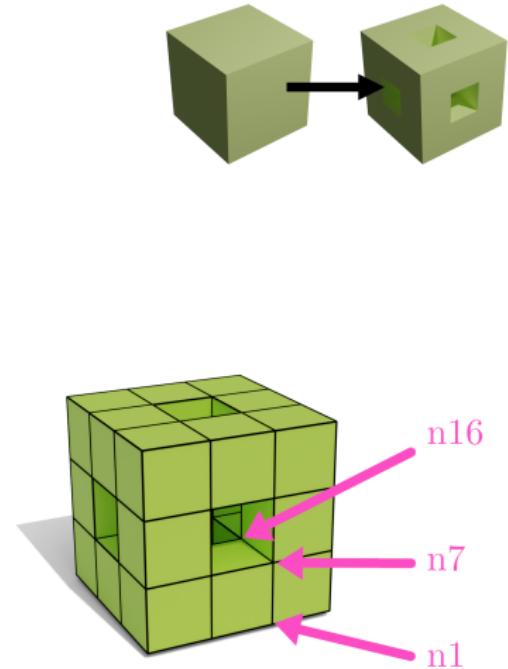
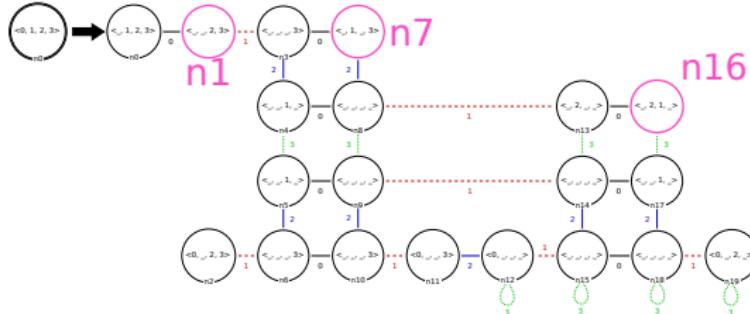
// face
Point3 p2 = Point3::middle(<0,1>_position(n0));

// weight
p2.scale(1.0);

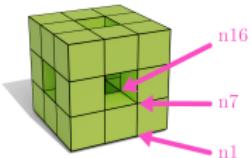
// added to the result
res.addVect(p2);

// return the value
return res;
```

Menger Sponge



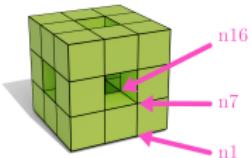
Menger Sponge



Node *n1*

```
Point3 res = new Point3(0.0,0.0,0.0);
Point3 p0 = Point3::middle(<0>_position(n0));
p0.scale(0.3333333134651184);
res.addVect(p0);
Point3 p1 = Point3::middle(<0>_position(n0));
p1.scale(0.6666666865348816);
res.addVect(p1);
return res;
```

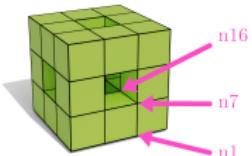
Menger Sponge



Node *n7*

```
Point3 res = new Point3(0.0,0.0,0.0);
Point3 p0 = Point3::middle(<>_position(n0));
p0.scale(0.3333333134651184);
res.addVect(p0);
Point3 p2 = Point3::middle(<0,1>_position(n0));
p2.scale(0.6666666865348816);
res.addVect(p2);
return res;
```

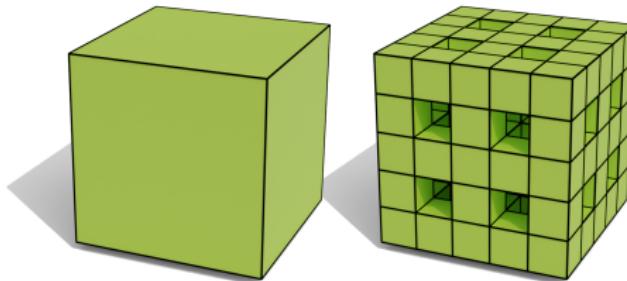
Menger Sponge



Node *n16*

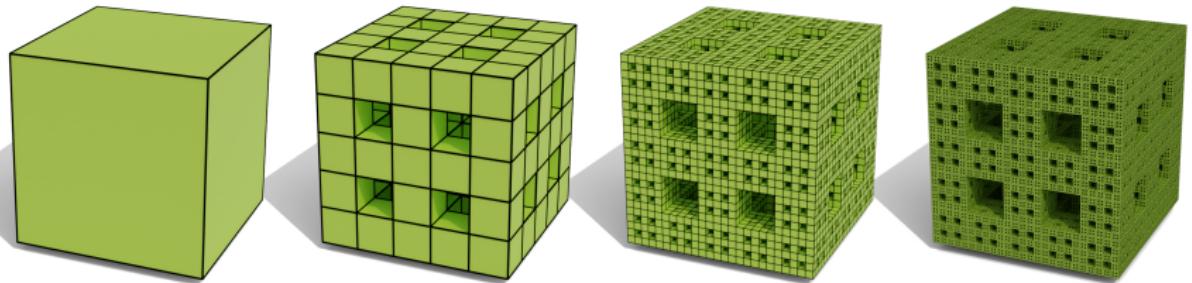
```
Point3 res = new Point3(0.0,0.0,0.0);
Point3 p0 = Point3::middle(<>_position(n0));
p0.scale(0.3333333134651184);
res.addVect(p0);
Point3 p3 = Point3::middle(<0,1,2>_position(n0));
p3.scale(0.6666666865348816);
res.addVect(p3);
return res;
```

$(2, 2, 2)$ -Menger Polycube¹



¹Richaume et al. 2019.

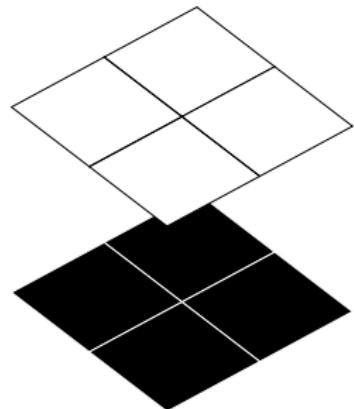
$(2, 2, 2)$ -Menger Polycube¹



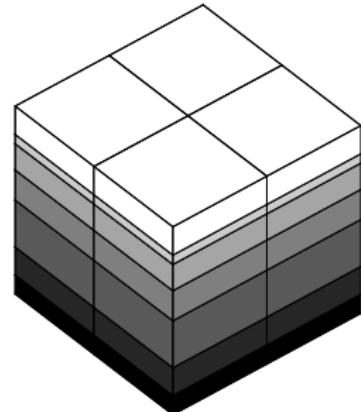
¹Richaume et al. 2019.

Geology inspired

Before



After



Positions and colors

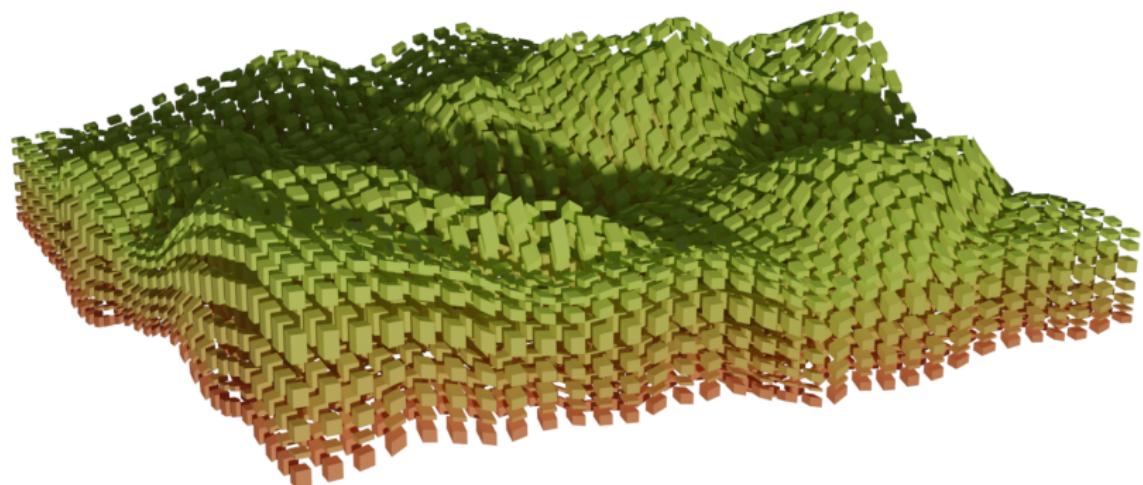
Geology inspired

Before



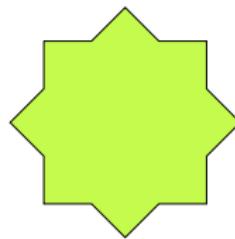
Geology inspired

After

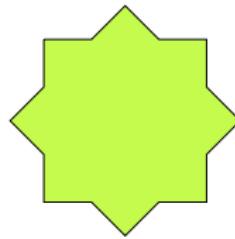


Limits

Von Koch's snowflake generated by L-systems

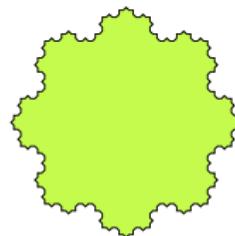
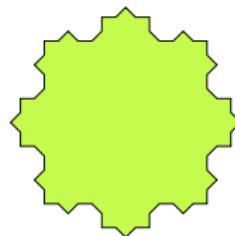
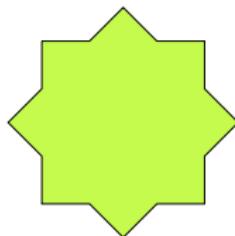


Inferred

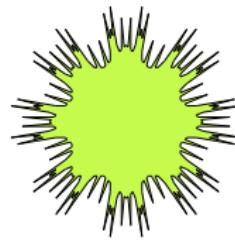
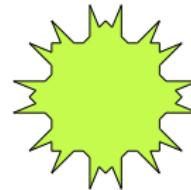
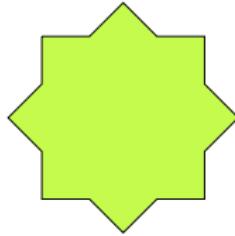


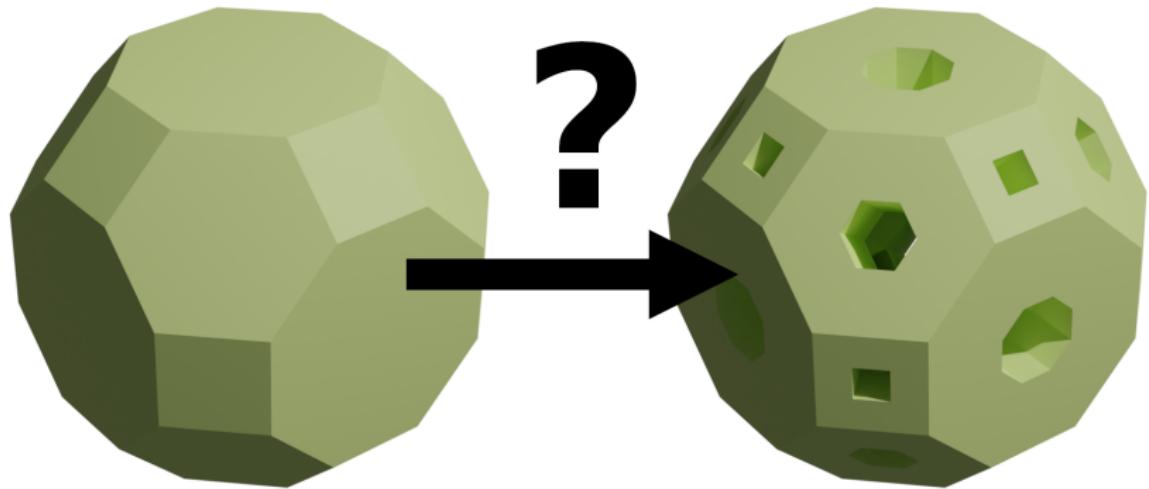
Limits

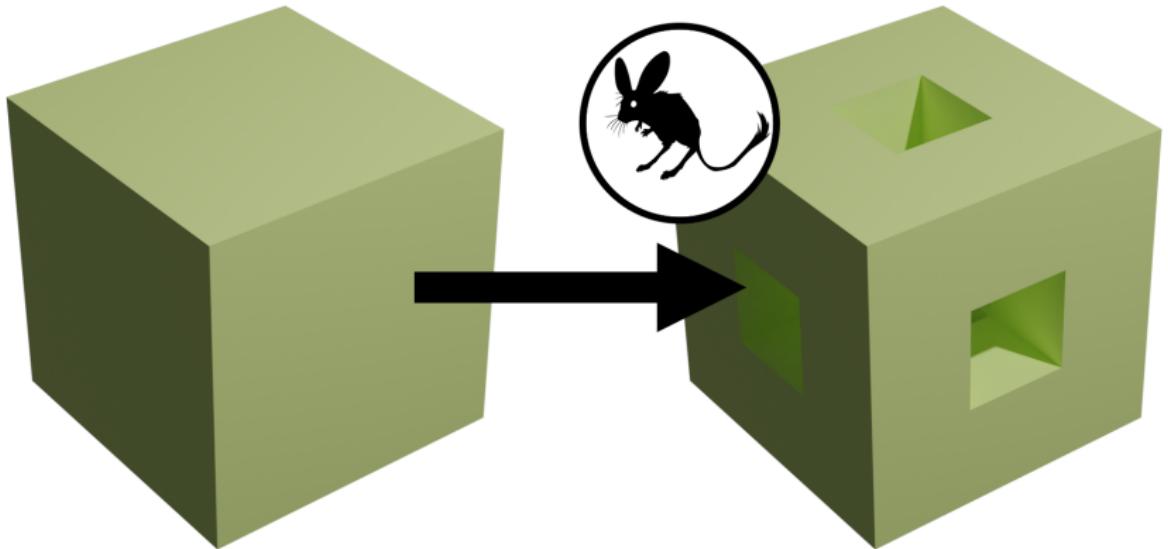
Von Koch's snowflake generated by L-systems



Inferred







Geometric inference and program synthesis

L

φ

Rule level

Rule scheme

Instantiated rule

Geometric inference and program synthesis

L

φ

Rule level	Rule scheme	Instantiated rule
Corresponds to	Affine combinations of points of interest	Concrete system derived from the example

Geometric inference and program synthesis

L

φ

Rule level	Rule scheme	Instantiated rule
Corresponds to	Affine combinations of points of interest	Concrete system derived from the example
Property	Finite	Encodes redundancies

Geometric inference and program synthesis

L

φ

Rule level	Rule scheme	Instantiated rule
Corresponds to	Affine combinations of points of interest	Concrete system derived from the example
Property	Finite	Encodes redundancies
Extend with	<ul style="list-style-type: none">• other points of interest• other computations	<ul style="list-style-type: none">• multi-examples• counter-examples

Geometric inference vs program synthesis?

Similarities

Geometric inference vs program synthesis?

Similarities

- Formal specification of the expected result

Geometric inference vs program synthesis?

Similarities

- Formal specification of the expected result
- DSL

Geometric inference vs program synthesis?

Similarities

- Formal specification of the expected result
- DSL
- Resolution delegated to a solver

Geometric inference vs program synthesis?

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- Formal specification of the expected result
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Differences

Geometric inference vs program synthesis?

Similarities

- Formal specification of the expected result
- DSL
- Resolution delegated to a solver

Differences

- Pretreatment induced by the topology

Geometric inference vs program synthesis?

Similarities

- Formal specification of the expected result
- DSL
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Differences

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- Exploit symmetries

Geometric inference vs program synthesis?

Similarities

- Formal specification of the expected result
- DSL
- Resolution delegated to a solver

Differences

- Pretreatment induced by the topology
- Exploit symmetries
- Not so easy to play with examples

Geometric inference vs program synthesis?

Similarities

- Formal specification of the expected result
- DSL
- Resolution delegated to a solver

Differences

- Pretreatment induced by the topology
- Exploit symmetries
- Not so easy to play with examples

Is there any added value in re-thinking in terms of program synthesis?

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